

## **Atsushi Yamashita, Ph.D.**

Associate Professor

Department of Precision Engineering, The University of Tokyo

7-3-1 Hongo, Bunkyo-ku, Tokyo 113-8656, Japan

Tel: +81-3-5841-6457 Fax: +81-3-5841-8548

E-mail: [yamashita@robot.t.u-tokyo.ac.jp](mailto:yamashita@robot.t.u-tokyo.ac.jp)

URL: <http://www.robot.t.u-tokyo.ac.jp/~yamashita/>



### **Education**

BE in Precision Machinery Engineering, The University of Tokyo, 1996.

ME in Precision Machinery Engineering, The University of Tokyo, 1998.

PhD in Precision Machinery Engineering, The University of Tokyo, 2001.

### **Professional Career**

2011-now: Associate Professor in Department of Precision Engineering, The University of Tokyo

2008-2011: Associate Professor in Department of Mechanical Engineering, Shizuoka University

2006-2007: Visiting Associate in Department of Mechanical Engineering, California Institute of Technology

2001-2008: Assistant Professor in Department of Mechanical Engineering, Shizuoka University

1998-2001: Junior Research Associate in the RIKEN (Institute of Physical and Chemical Research)

### **Research Interests**

Consumer Electronics, Robotics, Robot Vision, Computer Vision, Image Processing, Robot Motion Planning, Computer Graphics

### **Awards**

- 1) Best Paper Award, 2020 IEEE/SICE International Symposium on System Integration (SII2020), January 2020.
- 2) Best Presentation Award, 19th Annual Conference of System Integration Division, Society of Instrument and Control Engineers, March 2019.
- 3) Dean's Award (Research), School of Engineering, The University of Tokyo, February 2019.
- 4) JRM Best Paper Award, December 2018.
- 5) Best Paper Award, FA Foundation, December 2018.
- 6) JSME Medal for Outstanding Paper, The Japan Society of Mechanical Engineers, April 2018.
- 7) System Integration Award for Outstanding Presentation, System Integration Division, The Society of Instrument and Control Engineers, December 2017.
- 8) JSME Medal for Outstanding Paper, The Japan Society of Mechanical Engineers, April 2017.
- 9) Best Paper Award, International Workshop on Advanced Image Technology 2017 (IWAIT2017), January 2017.
- 10) Best Presentation Award, 17th Annual Conference of System Integration Division, Society of Instrument and Control Engineers, December 2016.
- 11) Best Paper Award, FA Foundation, December 2016.
- 12) Best Teaching Award, Faculty of Engineering, The University of Tokyo, December 2016.
- 13) Best Poster Award, MHS2016 (2016 International Symposium on Micro-Nano Mechatronics and Human Science), November 2016.
- 14) Best Conference Paper Award Finalist, 14th International Conference on Intelligent Autonomous Systems

(IAS-14), July 2016.

- 15) Best Paper Award, Japan Society for Precision Engineering, March 2016.
- 16) Best Presentation Award, 16th Annual Conference of System Integration Division, Society of Instrument and Control Engineers, December 2015.
- 17) Honorable Mention, ICAM2015 (6th International Conference on Advanced Mechatronics), December 2015.
- 18) Best Paper Award, ICAM2015 (6th International Conference on Advanced Mechatronics), December 2015.
- 19) Best Poster Award, MHS2015 (2015 International Symposium on Micro-Nano Mechatronics and Human Science), November 2015.
- 20) Best Paper Award, The Society of Instrument and Control Engineers, October 2015.
- 21) Best Paper Award, FA Foundation, December 2014.
- 22) Best Presentation Award in Rescue Robotics Session, 14th Annual Conference of System Integration Division, Society of Instrument and Control Engineers, December 2013.
- 23) JSME Education Award, Distinguished Text Book of “Robotics” and Improvement of Educational Methods, The Japan Society of Mechanical Engineers, April 2013.
- 24) Best Presentation Award in Rescue Robotics Session, 13rd Annual Conference of System Integration Division, Society of Instrument and Control Engineers, December 2012.
- 25) Funai Award, Funai Foundation for Information Technology, May 2011.
- 26) Certificate of Merit for ROBOMECH Outstanding Research Activity, Robotics and Mechatronics Division, The Japan Society of Mechanical Engineers, May 2011.
- 27) Best Paper Award, 4th Asia International Symposium on Mechatronics (AISM2010), December 2010.
- 28) Best Paper Award, 15th Robotics Symposia, March 2010.
- 29) Kisoi Motohiro Award, International Rescue System, January 2009.
- 30) Takayanagi-Kenkyu-Shorei Award, Hamamatsu-Denshi-Kogaku-Shoreikai, December 2007.
- 31) Young Investigation Excellence Award, Robotics Society of Japan, September 2006.
- 32) Best Paper Presentation Award, Institute of Electrical Engineers of Japan, September 2006.
- 33) Certificate of Merit for Best Presentation, Robotics and Mechatronics Division, The Japan Society of Mechanical Engineers, June 2005.
- 34) Young Investigation Excellence Award, Institute of Image Information and Television Engineers of Japan, December 2004.
- 35) Best Presentation Award in Rescue Robotics Session, 3rd Annual Conference of System Integration Division, Society of Instrument and Control Engineers, December 2002.
- 36) Ishi-Gakujyutu-Shorei Award by Sogo-Kenkyu-Shoreikai, March 2001 (Awarded for outstanding PhD thesis in Faculty of Engineering, The University of Tokyo).
- 37) Hatakeyama Award by Japan Society of Mechanical Engineers, March 1996 (Given to the Best Student of Department of Precision Machinery Engineering, The University of Tokyo).

### **Membership of Academic Societies**

- 1) Japan Society for Precision Engineering, JSPE (1996-)
- 2) Robotics Society of Japan, RSJ (1997-)
- 3) The Institute of Electrical and Electronics Engineers, IEEE (2000-)
- 4) The Institute of Electronics, Information and Communication Engineers, IEICE (2002-)
- 5) The Japan Society of Mechanical Engineers, JSME (2003-)
- 6) The Institute of Electrical Engineers of Japan, IEEEJ (2004-)
- 7) Information Processing Society of Japan, IPSJ (2004-)
- 8) The Institute of Image Information and Television Engineers, ITE (2004-)

- 9) The Society of Instrument and Control Engineers, SICE (2005-)
- 10) Association for Computing Machinery, ACM (2009-)
- 11) Society for Serviceology (2012-)
- 12) The Society of Automotive Engineers of Japan, JSAE (2017-)

### **Academic Activities**

- 1) Publication Co-chair, 2013 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2013) (2013/11/03~2013/11/07)
- 2) Program Chair, 2015 International Conference on Advanced Mechatronics (ICAM2015) (2015/12/05~2015/12/08)
- 3) General Co-chair, 1st International Symposium on Embodied-Brain Systems Science (EmboSS2016) (2016/05/08~2016/05/09)
- 4) Program Chair, 2016 IEEE International Conference on Robotics and Biomimetics (ROBIO2016) (2016/12/03~2016/12/07)
- 5) Session Organizer (Consumer Electronics Meets Robotics), 2019 IEEE 8th Global Conference on Consumer Electronics (GCCE2019) (2019/10/15~2019/10/18)

### **Reviewed Papers**

- 1) Atsushi Yamashita, Jun Ota, Kou Kawano, Masaki Fukuchi, Tamio Arai and Hajime Asama: "Motion Planning for Cooperative Manipulation of Object by Multiple Mobile Robots", The Transactions of The Institute of Electrical Engineers of Japan, Vol. 121-C, No. 3, pp. 549-556, May 2001, in Japanese.
- 2) Atsushi Yamashita, Tatsuya Kanazawa, Hajime Asama, Hayato Kaetsu, Isao Endo, Tamio Arai and Kazumi Sato: "Development of a Holonomic Omni-Directional Mobile Robot with Step-Climbing Ability", Journal of Robotics and Mechatronics, Vol. 13, No. 2, pp. 160-167, April 2001. [doi:10.20965/jrm.2001.p0160]
- 3) Atsushi Yamashita, Masaki Fukuchi, Jun Ota, Tamio Arai and Hajime Asama: "Motion Planning for Cooperative Transportation of a Large Object by Multiple Mobile Robots", Transactions of the Japan Society of Mechanical Engineers (Series C), Vol. 68, No. 665, pp. 165-172, January 2002, in Japanese. [doi:10.1299/kikaic.68.165]
- 4) Masayuki Kuramoto, Atsushi Yamashita, Toru Kaneko and Kenjiro T. Miura: "Removal of Adherent Waterdrops in Images Causing View Disturbance", The Journal of The Institute of Image Information and Television Engineers, Vol. 56, No. 5, pp. 853-857, May 2002, in Japanese. [doi:10.3169/itej.56.853]
- 5) Atsushi Kawarago, Atsushi Yamashita, Toru Kaneko and Kenjiro T. Miura: "Character Recognition for Books with Curved Surface using a Stereo Vision System", The Journal of The Institute of Image Information and Television Engineers, Vol. 56, No. 5, pp. 858-862, May 2002, in Japanese. [doi:10.3169/itej.56.858]
- 6) Kenjiro T. Miura, Junji Sone, Atsushi Yamashita, Toru Kaneko, Minoru Ueda and Minetada Osano: "Adaptive Refinement for B-spline Subdivision Curves", The Journal of Three Dimensional Images, Vol. 16, No. 4, pp. 74-78, December 2002.
- 7) Atsushi Yamashita, Tamio Arai, Jun Ota and Hajime Asama: "Motion Planning of Multiple Mobile Robots for Cooperative Manipulation and Transportation", IEEE Transactions on Robotics and Automation, Vol. 19, No. 2, pp. 223-237, April 2003. [doi:10.1109/TRA.2003.809592]
- 8) Atsushi Yamashita, Hajime Asama, Tamio Arai, Jun Ota and Toru Kaneko: "A Survey on Trends of Mobile Robot Mechanisms", The Journal of the Robotics Society of Japan, Vol. 21, No. 3, pp. 282-292, April 2003, in Japanese. [doi:10.7210/jrsj.21.282]
- 9) Atsushi Yamashita, Toru Kaneko, Shinya Matsushita, Kenjiro T. Miura and Suekichi Isogai: "Camera

Calibration and 3-D Measurement with an Active Stereo Vision System for Handling Moving Objects", *Journal of Robotics and Mechatronics*, Vol. 15, No. 3, pp. 304-313, June 2003. [doi:10.20965/jrm.2003.p0304]

- 10) Atsushi Yamashita, Toru Kaneko, Masaki Nishimura and Kenjiro T. Miura: "Restoration of Deteriorated Images in Contrary Weather by Changing the Camera Direction -Removal of View-Disturbing Waterdrops in Images by Using a Pan-Tilt Camera System-", *The Journal of The Institute of Image Information and Television Engineers*, Vol. 57, No. 10, pp. 1347-1353, October 2003, in Japanese. [doi:10.3169/itej.57.1347]
- 11) Kenjiro T. Miura, Masashi Adachi, Tsuneo Ikedo, Atsushi Yamashita and Toru Kaneko: "View-Dependent Refinement by Two-Stepped Catmull-Clark Subdivision", *The Journal of Three Dimensional Images*, Vol. 17, No. 4, pp. 33-38, December 2003.
- 12) Atsushi Yamashita, Toru Kaneko, Shinya Matsushita and Kenjiro T. Miura: "Region Extraction with Chromakey Using Stripe Backgrounds", *IEICE Transactions on Information and Systems*, Vol. 87-D, No. 1, pp. 66-73, January 2004.
- 13) Atsushi Yamashita, Toru Kaneko, Masaki Nishimura and Kenjiro T. Miura: "Removal of View-Disturbing Waterdrops in Images Using a Pan-Tilt Camera", *The Journal of Three Dimensional Images*, Vol. 18, No. 1, pp. 47-52, March 2004.
- 14) Atsushi Yamashita, Akihisa Nishimoto, Toru Kaneko and Kenjiro T. Miura: "Automatic Generation of Stereogram by Using Stripe Backgrounds", *The Journal of Three Dimensional Images*, Vol. 18, No. 1, pp. 53-58, March 2004.
- 15) Atsushi Yamashita, Tomoaki Harada, Toru Kaneko and Kenjiro T. Miura: "Virtual Wiper -Removal of Adherent Noises from Images of Dynamic Scenes by Using a Pan-Tilt Camera-", *Advanced Robotics*, Vol. 19, No. 3, pp. 295-310, March 2005. [doi:10.1163/1568553053583643]
- 16) Susumu Kato, Atsushi Yamashita, Toru Kaneko and Kenjiro T. Miura: "Three-dimensional Sensing in Underwater Environments with a Stereo Camera System", *The Journal of Three Dimensional Images*, Vol. 19, No. 4, pp. 102-107, December 2005.
- 17) Atsushi Yamashita, Takahiro Hara and Toru Kaneko: "Hammering Test with Image and Sound Signal Processing", *Transactions of the Japan Society of Mechanical Engineers (Series C)*, Vol. 72, No. 715, pp. 772-779, March 2006, in Japanese. [doi:10.1299/kikaic.72.772]
- 18) Atsushi Yamashita, Etsukazu Hayashimoto and Toru Kaneko: "3-D Shape Measurement of Objects in Liquid with a Laser Range Finder", *Transactions of the Japan Society of Mechanical Engineers (Series C)*, Vol. 72, No. 717, pp. 1506-1513, May 2006, in Japanese. [doi:10.1299/kikaic.72.1506]
- 19) Yuu Tanaka, Atsushi Yamashita, Toru Kaneko and Kenjiro T. Miura: "Removal of Adherent Waterdrops from Images Acquired with a Stereo Camera System", *IEICE Transactions on Information and Systems*, Vol. 89-D, No. 7, pp. 2021-2027, July 2006.
- 20) Hiroki Agata, Atsushi Yamashita and Toru Kaneko: "Chroma Key Using a Checker Pattern Background", *IEICE Transactions on Information and Systems*, Vol. 90-D, No. 1, pp. 242-249, January 2007.
- 21) Atsushi Yamashita, Hirokazu Higuchi and Toru Kaneko: "3-D Measurement of Objects in Water Using the Light Stripe Projection Method", *Journal of the Japan Society for Precision Engineering*, Vol. 73, No. 2, pp. 265-269, February 2007, in Japanese. [doi:10.2493/jjspe.73.265]
- 22) Atsushi Yamashita, Tomoaki Harada and Toru Kaneko: "Three-Dimensional Environment Modeling from Images Acquired with an Omni-Directional Camera Mounted on a Mobile Robot by Structure from Motion", *Transactions of the Japan Society of Mechanical Engineers (Series C)*, Vol. 73, No. 726, pp. 512-519, February 2007, in Japanese. [doi:10.1299/kikaic.73.512]
- 23) Atsushi Yamashita, Hiroki Agata and Toru Kaneko: "Stripe Chromakey Using Active Contour Models", *The Journal of The Institute of Image Information and Television Engineers*, Vol. 61, No. 2, pp. 189-197,

February 2007, in Japanese. [doi:10.3169/itej.61.189]

- 24) Atsushi Yamashita, Masayuki Kuramoto and Toru Kaneko: "Removal of Adherent Noises in Images by Using Multiple Cameras", The Transactions of The Institute of Electrical Engineers of Japan, Vol. 127-C, No. 4, pp. 480-488, April 2007, in Japanese. [doi:10.1541/ieej.127.480]
- 25) Isao Fukuchi, Atsushi Yamashita, Toru Kaneko and Kenjiro T. Miura "Removing Adherent Noise from Image Sequences in Rainy Weather by Spatio-Temporal Image Processing", The Journal of The Institute of Image Information and Television Engineers, Vol. 62, No. 5, pp. 771-777, May 2008, in Japanese. [doi:10.3169/itej.62.771]
- 26) Atsushi Yamashita, Masayuki Kuramoto and Toru Kaneko: "Removal of Adherent Noises in Images by Using Multiple Cameras", Electrical Engineering in Japan, Vol. 164, No. 3, pp. 50-59, August 2008. [doi:10.1002/eej.20697]
- 27) Atsushi Yamashita, Takahiro Hara and Toru Kaneko: "Hammering Test with Integration of Image and Sound Signal Processing", Journal of Environment and Engineering, Vol. 3, No. 2, pp. 363-373, 2008. [doi:10.1299/jee.3.363]
- 28) Ryosuke Kawanishi, Atsushi Yamashita and Toru Kaneko: "Three-Dimensional Environment Model Construction from an Omnidirectional Image Sequence", Journal of Robotics and Mechatronics, Vol. 21, No. 5, pp. 574-582, October 2009. [doi:10.20965/jrm.2009.p0574]
- 29) Ryosuke Kawanishi, Atsushi Yamashita and Toru Kaneko: "Three-dimensional Environment Modeling Based on Structure From Motion with Feature Point and Edge Information in Omnidirectional Image Sequence", The Transactions of The Institute of Electrical Engineers of Japan, Vol. 130-C, No. 9, pp. 1494-1503, September 2010, in Japanese. [doi:10.1541/ieej.130.1494]
- 30) Kenki Matsui, Atsushi Yamashita and Toru Kaneko: "Self-Localization and 3-D Model Construction of Pipe by Rangefinder Constructed with Omni-Directional Laser and Omni-Directional Camera", The Transactions of The Institute of Electrical Engineers of Japan, Vol. 130-C, No. 9, pp. 1504-1512, September 2010, in Japanese. [doi:10.1541/ieej.130.1504]
- 31) Noriko Nagata, Hidehiro Ohki, Kunihiro Kato, Hiroyasu Koshimizu, Ryusuke Sagawa, Takayuki Fujiwara, Atsushi Yamashita and Manabu Hashimoto: "Current Issues and Trends on Multi-Dimensional Sensing Technologies in Digital Media", The Transactions of The Institute of Electrical Engineers of Japan, Vol. 131-D, No. 4, pp. 433-440, April 2011, in Japanese. [doi:10.1541/ieej.131.433]
- 32) So Kuno, Atsushi Yamashita and Toru Kaneko: "Assisting System in Touch-Panel Operation Using Stereo Camera", The Transactions of The Institute of Electrical Engineers of Japan, Vol. 131-D, No. 4, pp. 458-465, April 2011, in Japanese. [doi:10.1541/ieej.131.458]
- 33) Rie Miyaki, Atsushi Yamashita and Toru Kaneko: "Color Information Presentation for Color Vision Defectives by Using a Projector Camera System", The Transactions of The Institute of Electrical Engineers of Japan, Vol. 131-D, No. 4, pp. 497-504, April 2011, in Japanese. [doi:10.1541/ieej.131.497]
- 34) Atsushi Yamashita, Masaaki Kitaoka and Toru Kaneko: "Motion Planning of Biped Robot Equipped with Stereo Camera Using Grid Map", International Journal of Automation Technology, Vol. 5, No. 5, pp. 639-647, September 2011. [doi:10.20965/ijat.2011.p0639]
- 35) Ryosuke Kawanishi, Atsushi Yamashita and Toru Kaneko: "Construction of 3-D Environment Model based on Automatic Baseline Determined Structure from Motion Constrained by Point and Line Features by Using Omnidirectional Camera", The Journal of the Robotics Society of Japan, Vol. 30, No. 4, pp. 399-410, May 2012, in Japanese. [doi:10.7210/jrsj.30.399]
- 36) Guanghui Li, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Moving Task Allocation and Reallocation Method Based on Body Expansion Behaviour for Distributed Multi-robot Coordination", International Journal of Mechatronics and Automation, Vol. 2, No. 4, pp. 240-261, 2012.

[doi:10.1504/IJMA.2012.050495]

- 37) Ryosuke Kawanishi, Atsushi Yamashita, Toru Kaneko and Hajime Asama: "Parallel Line-based Structure from Motion by Using Omnidirectional Camera in Textureless Scene", *Advanced Robotics*, Vol. 27, No. 1, pp. 19-32, January 2013. [doi:10.1080/01691864.2013.751160]
- 38) Gakuto Masuyama, Atsushi Yamashita and Hajime Asama: "Reinforcement Learning Based on Intrinsic Motivation and Temporal Abstraction via Transformation Invariance", *Transactions of the Japan Society of Mechanical Engineers (Series C)*, Vol. 79, No. 798, pp. 289-303, February 2013, in Japanese. [doi:10.1299/kikaic.79.289]
- 39) Yusuke Tamura, Shunsuke Hamasaki, Atsushi Yamashita and Hajime Asama: "Collision Avoidance of Mobile Robot Based on Prediction of Human Movement According to Environments", *Transactions of the Japan Society of Mechanical Engineers (Series C)*, Vol. 79, No. 799, pp. 617-628, March 2013, in Japanese. [doi:10.1299/kikaic.79.617]
- 40) Tatsuya Naruse, Atsushi Yamashita, Toru Kaneko and Yuichi Kobayashi: "3D Measurement of Objects in Water Using Fish-eye Stereo Camera", *Journal of the Japan Society for Precision Engineering*, Vol. 79, No. 4, pp. 344-348, April 2013, in Japanese. [doi:10.2493/jjspe.79.344]
- 41) Wataru Kumahara, Gakuto Masuyama, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Mobile Robot Navigation Based on Local Route Information and Pedestrians' Flow", *Journal of the Japan Society for Precision Engineering*, Vol. 79, No. 4, pp. 349-355, April 2013, in Japanese. [doi:10.2493/jjspe.79.349]
- 42) Guanghui Li, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Effective Improved Artificial Potential Field Based Regression Search Method for Autonomous Mobile Robot Path Planning", *International Journal of Mechatronics and Automation*, Vol. 3, No. 3, pp. 141-170, 2013. [doi:10.1504/IJMA.2013.055612]
- 43) Yusuke Tamura, Yoshitaka Terada, Atsushi Yamashita and Hajime Asama, "Modelling Behaviour Patterns of Pedestrians for Mobile Robot Trajectory Generation", *International Journal of Advanced Robotic Systems*, Vol. 10, 310, pp. 1-11, 2013. [doi:10.5772/56668]
- 44) Ryuho Kataoka, Yoshizumi Miyoshi, Kai Shigematsu, Donald Hampton, Yoshiki Mori, Takayuki Kubo, Atsushi Yamashita, Masayuki Tanaka, Toshiyuki Takahei, Taro Nakai, Hiroko Miyahara and Kazuo Shiokawa: "Stereoscopic Determination of All-sky Altitude Map of Aurora Using Two Ground-based Nikon DSLR Cameras", *Annales Geophysicae*, Vol. 31, No. 9, pp. 1543-1548, September 2013. [doi:10.5194/angeo-31-1543-2013]
- 45) Hiroto Ibe, Atsushi Yamashita, Toru Kaneko and Yuichi Kobayashi: "3D Measurement of Submerged Object in Transparent Vessel Using Laser Range Finder Mounted on Manipulator", *The Journal of The Institute of Image Information and Television Engineers*, Vol. 67, No. 11, pp. J379-J387, November 2013, in Japanese. [doi:10.3169/itej.67.J379]
- 46) Wataru Kumahara, Gakuto Masuyama, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Navigation System for Mobile Robot Based on Pedestrian Flow under Dynamic Environment", *Transactions of the Society of Instrument and Control Engineers*, Vol. 50, No. 1, pp. 58-67, January 2014, in Japanese. [doi:10.9746/sicetr.50.58]
- 47) Qi An, Yuki Ishikawa, Junki Nakagawa, Hiroyuki Oka, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "Measurement of Just Noticeable Difference of Hip Joint for Implementation of Self-efficacy: In Active and Passive Sensation and in Different Speed", *Advanced Robotics*, Vol. 28, No. 7, pp. 505-511, January 2014. [doi:10.1080/01691864.2013.876938]
- 48) Masashi Awai, Atsushi Yamashita, Takahito Shimizu, Toru Kaneko, Yuichi Kobayashi and Hajime Asama: "Development of Mobile Robot System Equipped with Camera and Laser Range Finder Realizing HOG-Based Person Following and Autonomous Returning", *Journal of Robotics and Mechatronics*, Vol. 26,

No. 1, pp. 68-77, February 2014. [doi:10.20965/jrm.2014.p0068]

- 49) Qi An, Yuki Ishikawa, Tetsuro Funato, Shinya Aoi, Hiroyuki Oka, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "Muscle Synergy Analysis of Human Standing-up Motion in Different Seat Heights and Speeds", Transactions of the Society of Instrument and Control Engineers, Vol. 50, No. 8, pp. 560-568, August 2014, in Japanese. [doi:10.9746/sicetr.50.560]
- 50) Kazuhiro Chayama, Akira Fujioka, Kenji Kawashima, Hiroshi Yamamoto, Yasushi Nitta, Chikao Ueki, Atsushi Yamashita and Hajime Asama: "Technology of Unmanned Construction System in Japan", Journal of Robotics and Mechatronics, Vol. 26, No. 4, pp. 403-417, August 2014. [doi:10.20965/jrm.2014.p0403]
- 51) Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Automated Recognition of Material Condition Using Boosting Algorithm in Hammering Test", Journal of the Japan Society for Precision Engineering, Vol. 80, No. 9, pp. 844-850, September 2014, in Japanese. [doi:10.2493/jjspe.80.844]
- 52) Kohei Hanatani, Hiroshi Yamakawa, Yuki Ishikawa, Qi An, Atsushi Yamashita and Hajime Asama: "Development of Stress Measurement System during Human Stand-up Motion Using Accurate Shape Knee Joint Model", Journal of the Japan Society for Precision Engineering, Vol. 81, No. 1, pp. 99-104, January 2015, in Japanese. [doi:10.2493/jjspe.81.99]
- 53) Junki Nakagawa, Qi An, Yuki Ishikawa, Hiroyuki Oka, Kaoru Takakusaki, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "Analysis of Human Motor Skill in Dart Throwing Motion at Different Distance", SICE Journal of Control, Measurement, and System Integration, Vol. 8, No. 1, pp. 79-85, January 2015. [doi:10.9746/jcmsi.8.79]
- 54) Naoki Ibe, Gakuto Masuyama, Atsushi Yamashita and Hajime Asama: "Generation of Give-way Behavior of Pedestrian Model with Probabilistic Intention for Mobile Robot Navigation", Transactions of the JSME, Vol. 81, No. 821, 14-00330, pp. 1-14, January 2015, in Japanese. [doi:10.1299/transjsme.14-00330]
- 55) Tsukasa Suwazono, Norihito Nakamura and Atsushi Yamashita: "Development of the Remote-controlled Platform Truck for Handling Heavy Object and the Remote Control Human Interface for the Disaster Response", Advanced Robotics, Vol. 29, No. 3, pp. 165-169, February 2015. [doi:10.1080/01691864.2014.1001787]
- 56) Takaaki Sato, Horomitsu Fujii, Alessandro Moro, Kazuya Sugimoto, Akira Nozue, Yoichi Mimura, Katsumi Obata, Atsushi Yamashita and Hajime Asama: "Development of Bird's-eye View System in Unmanned Construction", Transactions of the JSME, Vol. 81, No. 823, 14-00031, pp. 1-13, March 2015, in Japanese. [doi:10.1299/transjsme.14-00031]
- 57) Yonghoon Ji, Atsushi Yamashita and Hajime Asama: "RGB-D SLAM Using Vanishing Point and Door Plate Information in Corridor Environment", Intelligent Service Robotics, Vol. 8, No. 2, pp. 105-114, March 2015. [doi:10.1007/s11370-015-0166-1]
- 58) Wen Wen, Atsushi Yamashita and Hajime Asama: "The Sense of Agency during Continuous Action: Performance is More Important than Action-Feedback Association", PLoS ONE, Vol. 10, No. 4, e0125226, pp. 1-16, April 2015. [doi:10.1371/journal.pone.0125226]
- 59) Jonghoon Im, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Correction of Over and Under Exposure Images Using Multiple Lighting System", E-Journal of Advanced Maintenance, Vol. 7, No. 1, pp. 50-58, May 2015.
- 60) Soichiro Morishita, Ichiro Fukuda, Yoshikazu Arai, Atsushi Yamashita and Hajime Asama: "Identification of the Person in Video Sequence by Using UHF band RFID System", Journal of the Japan Society for Precision Engineering, Vol. 81, No. 6, pp. 589-597, 2015, in Japanese. [doi:10.2493/jjspe.81.589]
- 61) Takuma Tsuji, Shunsuke Hamasaki, Takaki Maeda, Motoichiro Kato, Hiroyuki Oka, Hiroshi Yamakawa, Kaoru Takakusaki, Atsushi Yamashita and Hajime Asama: "Analysis of Electromyography and Skin Conductance Response during Rubber Hand Illusion", Transactions of the Society of Instrument and Control

- Engineers, Vol. 51, No. 6, pp. 440-447, June 2015, in Japanese. [doi:10.9746/sicetr.51.440]
- 62) Soichiro Morishiha, Takehiro Watanabe, Kuniaki Kawabata, Yoshikazu Arai, Atsushi Yamashita, Hajime Asama and Taketoshi Mishima: "Particle Counting Method for Asbestos Qualitative Analysis Based on Multi-Resolution Analysis", *Journal of the Japan Society for Precision Engineering*, Vol. 81, No. 10, pp. 930-935, October 2015, in Japanese. [doi:10.2493/jjspe.81.930]
- 63) Wen Wen, Atsushi Yamashita and Hajime Asama: "The Influence of Action-Outcome Delay and Arousal on Sense of Agency and the Intentional Binding Effect", *Consciousness and Cognition*, Vol. 36, pp. 87-95, November 2015. [doi:10.1016/j.concog.2015.06.004]
- 64) Hirotoshi Ibe, Yuichi Kobayashi, Toru Kaneko and Atsushi Yamashita: "Three-Dimensional Measurement of Underwater Objects in a Rectangular Vessel by Using Bi-Path Stereoscopy", *Journal of the Japan Society for Precision Engineering*, Vol. 81, No. 12, pp. 1093-1101, December 2015, in Japanese. [doi:10.2493/jjspe.81.1093]
- 65) Yusuke Tanaka, Yonghoon Ji, Atsushi Yamashita and Hajime Asama: "Adaptive Traversability Analysis and Behavior Generation Method for Mobile Robots on Rough Terrain", *Journal of the Japan Society for Precision Engineering*, Vol. 81, No. 12, pp. 1119-1126, December 2015, in Japanese. [doi:10.2493/jjspe.81.1119]
- 66) Hiromitsu Fujii, Kazuya Sugimoto, Atsushi Yamashita and Hajime Asama: "Online Half Diminished-Reality Imaging Using Multiple RGB-D Sensors for Remote Control Robot", *Journal of the Japan Society for Precision Engineering*, Vol. 81, No. 12, pp. 1185-1192, December 2015, in Japanese. [doi:10.2493/jjspe.81.1185]
- 67) Ren Komatsu, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Development of Bird's-eye View System for Teleoperated Robot in Camera Troubles with Arrangement Design of Camera", *Journal of the Japan Society for Precision Engineering*, Vol. 81, No. 12, pp. 1206-1212, December 2015, in Japanese. [doi:10.2493/jjspe.81.1206]
- 68) Wen Wen, Atsushi Yamashita and Hajime Asama: "The Influence of Goals on Sense Control", *Consciousness and Cognition*, Vol. 37, pp. 83-90, December 2015. [doi:10.1016/j.concog.2015.08.012]
- 69) Daiki Kawakami, Kaito Makino, Yuichi Kobayashi, Toru Kaneko, Atsushi Yamashita and Hajime Asama: "Projector Camera System Presenting Color Information for the Color Vision Deficient", *Journal of Advanced Computational Intelligence and Intelligent Informatics*, Vol. 20, No. 1, pp. 26-32, January 2016. [doi:10.20965/jaciii.2016.p0026]
- 70) Wen Wen, Atsushi Yamashita and Hajime: "Divided Attention and Processes Underlying Sense of Agency", *Frontiers in Psychology*, Vol. 7, No. 35, pp. 1-8, January 2016. [doi:10.3389/fpsyg.2016.00035]
- 71) Qi An, Koushirou Yanai, Junki Nakagawa, Wen Wen, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "Skill Training System for Rowing Motion Using Integrated Presentation of Motion and Muscle Activation", *Transactions of the JSME*, Vol. 82, No. 834, 15-00424, pp. 1-11, February 2016, in Japanese. [doi:10.1299/transjsme.15-00424]
- 72) Hiromitsu Fujii, Atsushi Yamashita and Hajime: "Hammering Diagnosis Algorithm with Automated Calibration", *Transactions of the JSME*, Vol. 82, No. 834, 15-00426, pp. 1-18, February 2016, in Japanese. [doi:10.1299/transjsme.15-00426]
- 73) Akira Takeuchi, Hiromitsu Fujii, Atsushi Yamashita, Masayuki Tanaka, Ryuho Kataoka, Yoshizumi Miyoshi, Masatoshi Okutomi and Hajime Asama: "Aurora 3D-measurement from Whole-sky Time Series Image Using Fish-eye Stereo Camera", *Transactions of the JSME*, Vol. 82, No. 834, 15-00428, pp. 1-17, February 2016, in Japanese. [doi:10.1299/transjsme.15-00428]
- 74) Yuichi Kobayashi, Yutaro Ohshima, Toru Kaneko and Atsushi Yamashita: "Meal Support System with Spoon Using Laser Range Finder and Manipulator", *International Journal of Robotics and Automation*, Vol. 31, No.



- 3, pp. 1-10, May 2016. [doi:10.2316/Journal.206.2016.3.206-4342]
- 75) Wen Wen, Katsutoshi Muramatsu, Shunsuke Hamasaki, Qi An, Hiroshi Yamakawa, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Goal-directed Movement Enhances Body Representation Updating", *Frontiers in Human Neuroscience*, Vol. 10, No. 329, pp. 1-10, June 2016. [doi:10.3389/fnhum.2016.00329]
- 76) Rin Minohara, Wen Wen, Shunsuke Hamasaki, Takaki Maeda, Motoichiro Kato, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "Strength of Intentional Effort Enhances the Sense of Agency", *Frontiers in Psychology*, Vol. 7, No. 1165, pp. 1-5, July 2016. [doi:10.3389/fpsyg.2016.01165]
- 77) Yonghoon Ji, Atsushi Yamashita and Hajime Asama, "Indoor Positioning System Based on Camera Sensor Network for Mobile Robot Localization in Indoor Environments", *Journal of Institute of Control, Robotics and Systems*, Vol. 22, No. 11, pp. 952-959, November 2016, (in Korean). [doi:10.5302/J.ICROS.2016.16.0079]
- 78) Hanwool Woo, Yonghoon Ji, Hitoshi Kono, Yusuke Tamura, Yasuhide Kuroda, Takashi Sugano, Yasunori Yamamoto, Atsushi Yamashita and Hajime Asama: "Automatic Detection Method of Lane-Changing Intentions Based on Relationship with Adjacent Vehicles Using Artificial Potential Fields", *International Journal of Automotive Engineering*, Vol. 7, No. 4, pp. 127-134, November 2016. [doi:10.20485/jsaeijae.7.4\_127]
- 79) Akira Shibata, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Scale-Reconstructable Structure from Motion Using a Refractive Plate and a Single Camera", *Journal of the Japan Society for Precision Engineering*, Vol. 82, No. 12, pp. 1045-1053, December 2016, in Japanese. [doi:10.2493/jjspe.82.1045]
- 80) Ningjia Yang, Qi An, Hiroshi Yamakawa, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Muscle Synergy Structure using Different Strategies in Human Standing-up Motion", *Advanced Robotics*, Vol. 31, No. 1-2, pp. 40-54, January 2017. [doi:10.3389/10.1080/01691864.2016.1238781]
- 81) Yuki Ishikawa, Qi An, Junki Nakagawa, Hiroyuki Oka, Tetsuro Yasui, Michio Tojima, Haruhi Inokuchi, Nobuhiko Haga, Hiroshi Yamakawa, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Gait Analysis of Patients with Knee Osteoarthritis by Using Elevation Angle: Confirmation of the Planar Law and Analysis of Angular Difference in the Approximate Plane", *Advanced Robotics*, Vol. 31, No. 1-2, pp. 68-79, January 2017. [doi:10.3389/10.1080/01691864.2016.1229217]
- 82) Yonghoon Ji, Atsushi Yamashita and Hajime Asama: "Automatic Calibration of Camera Sensor Networks Based on 3D Texture Map Information", *Robotics and Autonomous Systems*, Vol. 87, pp. 313-328, January 2017. [doi:10.1016/j.robot.2016.09.015]
- 83) Tatsuya Kittaka, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Seeing through Obstacles from Arbitrary Viewpoints by Using Movable RGB-D Sensors", *Journal of the Japan Society for Precision Engineering*, Vol. 83, No. 3, pp. 235-244, March 2017, in Japanese. [doi:10.2493/jjspe.83.235]
- 84) Hanwool Woo, Yonghoon Ji, Hitoshi Kono, Yusuke Tamura, Yasuhide Kuroda, Takashi Sugano, Yasunori Yamamoto, Atsushi Yamashita and Hajime Asama: "Lane-Change Detection Based on Vehicle-Trajectory Prediction", *IEEE Robotics and Automation Letters*, Vol. 2, No. 2, pp. 1109-1116, April 2017. [doi:10.1109/LRA.2017.2660543]
- 85) Hitoshi Kono, Musab Obaid Alhammadi, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Distributed Cooperative Fault Diagnosis Method for Internal Components of Robot Systems", *International Journal of Intelligent Systems and Applications in Robotics*, Vol. 8, No. 1, pp. 1-11, April 2017.
- 86) Jun Younes Louhi Kasahara, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Unsupervised Learning Approach to Automation of Hammering Test Using Topological Information", *ROBOMECH Journal*, Vol. 4, 13, pp. 1-10, May 2017. [doi:10.1186/s40648-017-0081-7]
- 87) Wen Wen, Daisuke Tomoi, Hiroshi Yamakawa, Shunsuke Hamasaki, Kaoru Takakusaki, Qi An, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Continuous Estimation of Stress Using Physiological

- Signals during a Car Race", *Psychology*, Vol. 8, pp. 978-986, May 2017. [doi:10.4236/psych.2017.87064]
- 88) Yoshiro Hada, Manabu Nakao, Moyuru Yamada, Hiroki Kobayashi, Naoyuki Sawasaki, Katsunori Yokoji, Satoshi Kanai, Fumiki Tanaka, Hiroaki Date, Sarthak Pathak, Atsushi Yamashita, Manabu Yamada and Toshiya Sugawara: "Development of a Bridge Inspection Support System Using Two-Wheeled Multicopter and 3D Modeling Technology", *Journal of Disaster Research*, Vol. 12, No. 3, pp. 593-606, June 2017. [doi:10.20965/jdr.2017.p0593]
- 89) Sarthak Pathak, Alessandro Moro, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Spherical Video Stabilization by Estimating Rotation from Dense Optical Flow Fields", *Journal of Robotics and Mechatronics*, Vol. 29, No. 3, pp. 566-579, June 2017. [doi:10.20965/jrm.2017.p0566]
- 90) Wen Wen, Atsushi Yamashita and Hajime Asama: "Measurement of the Perception of Control during Continuous Movement Using Electroencephalography", *Frontiers in Human Neuroscience*, Vol. 11, Article 392, pp. 1-7, July 2017. [doi:10.3389/fnhum.2017.00392]
- 91) Wen Wen, Atsushi Yamashita and Hajime Asama: "The Influence of Performance on Action-Effect Integration in Sense of Agency", *Consciousness and Cognition*, Vol. 53, pp. 89-98, August 2017. [doi:10.1016/j.concog.2017.06.008]
- 92) Doyeon Kim, Hanwool Woo, Yonghoon Ji, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Effect of Detector Pose Uncertainty in Localization of Radiation Sources", *E-Journal of Advanced Maintenance*, Vol. 9, No. 2, pp. 97-103, August 2017.
- 93) Veerachart Srisamosorn, Noriaki Kuwahara, Atsushi Yamashita, Taiki Ogata and Jun Ota: "Human-tracking System Using Quadrotors and Multiple Environmental Cameras for Face-tracking Application", *International Journal of Advanced Robotic Systems*, Vol. 14, No. 5, pp. 1-18, September 2017. [doi:10.1177/1729881417727357]
- 94) Sarthak Pathak, Alessandro Moro, Atsushi Yamashita and Hajime Asama: "Optical Flow-based Epipolar Estimation of Spherical Image Pairs for 3D Reconstruction", *SICE Journal of Control, Measurement, and System Integration*, Vol. 10, No. 5, pp. 476-485, September 2017. [doi:10.9746/jcmsi.10.476]
- 95) Hitoshi Kono, Tsuyoshi Suzuki, Akiya Kamimura, Kohji Tomita, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Automatic Convergence Estimation by Utilizing Fractal Dimensional Analysis for Reinforcement Learning", *Journal of Instrumentation, Automation and Systems*, Vol. 3, No. 3, pp. 58-70, September 2016. [doi:10.21535/jias.v3i3.934]
- 96) Binbin Xu, Sarthak Pathak, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Spatio-temporal Video Completion in Spherical Image Sequences", *IEEE Robotics and Automation Letters*, Vol. 2, No. 4, pp. 2032-2039, October 2017. [doi:10.1109/LRA.2017.2718106]
- 97) Shunsuke Hamasaki, Qi An, Masataka Murabayashi, Yusuke Tamura, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "Evaluation of the Effect of Prime Stimulus on Sense of Agency in Stop Operation of the Object in Circular Motion", *Journal of Advanced Computational Intelligence and Intelligent Informatics*, Vol. 21, No. 7, pp. 1161-1171, November 2017. [doi:10.20965/jaciii.2017.p1161]
- 98) Yukari Okumura, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Robust Scale-Reconstructible Structure from Motion Using Refraction against Measurement Error", *Journal of the Japan Society for Precision Engineering*, Vol. 83, No. 12, pp. 1201-1208, December 2017, in Japanese. [doi:10.2493/jjspe.83.1201]
- 99) Tsubasa Goto, Sarthak Pathak, Yonghoon Ji, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "3D-2D Matching of Line Features for Spherical Camera Localization in Man-made Environment", *Journal of the Japan Society for Precision Engineering*, Vol. 83, No. 12, pp. 1216-1223, December 2017, in Japanese. [doi:10.2493/jjspe.83.1209]
- 100) Yasuyuki Awashima, Ren Komatsu, Hiromitsu Fujii, Yusuke Tamura, Atsushi Yamashita and Hajime

- Asama: "Visualization of Obstacles on Bird's-eye View by Omnidirectional 3D Ranging Using LiDAR for Remote Controlled Robot", *Journal of the Japan Society for Precision Engineering*, Vol. 83, No. 12, pp. 1216-1223, December 2017, in Japanese. [doi:10.2493/jjspe.83.1216]
- 101) Hanwool Woo, Yonghoon Ji, Yusuke Tamura, Yasuhide Kuroda, Takashi Sugano, Yasunori Yamamoto, Atsushi Yamashita and Hajime Asama: "Dynamic State Estimation of Driving Style Based on Driving Risk Feature", *International Journal of Automotive Engineering*, Vol. 9, No. 1, pp. 31-38, March 2018. [doi:10.20485/jsaeijae.9.1\_31]
- 102) Hirotoshi Ibe, Satoshi Ishikawa, Yuichi Kobayashi, Toru Kaneko, Susumu Ishihara and Atsushi Yamashita: "Another View Point Image Generation with Shifted Perspective Using Two In-Vehicle Camera Images for Car Navigation System Based on Vehicular Ad-Hoc Networks", *Journal of the Japan Society for Precision Engineering*, Vol. 84, No. 4, pp. 356-363, April 2018, in Japanese. [doi:10.2493/jjspe.84.356]
- 103) Hiroshi Higuchi, Hiromitsu Fujii, Atsushi Taniguchi, Masahiro Watanabe, Atsushi Yamashita and Hajime Asama: "3D Measurement from the Inside of Large Structure Using Ring Laser and a Camera", *The Journal of the Robotics Society of Japan*, Vol. 36, No. 3, pp. 222-232, April 2018, in Japanese. [doi:10.7210/jrsj.36.222]
- 104) Renato Miyagusuku, Atsushi Yamashita and Hajime Asama: "Precise and Accurate Wireless Signal Strength Mappings Using Gaussian Processes and Path Loss Models", *Robotics and Autonomous Systems*, Vol. 103, pp. 134-150, May 2018. [doi:10.1016/j.robot.2018.02.011]
- 105) Hiroki Kogami, Qi An, Ningjia Yang, Hiroshi Yamakawa, Yusuke Tamura, Atsushi Yamashita, Hajime Asama, Shingo Shimoda, Hiroshi Yamasaki, Matti Itkonen, Fady Alnajjar, Noriaki Hattori, Makoto Kinomoto, Kouji Takahashi, Takanori Fujii, Hironori Otomune and Ichiro Miyai: "Effect of Physical Therapy on Muscle Synergy Structure during Standing-up Motion of Hemiplegic Patients", *IEEE Robotics and Automation Letters*, Vol. 3, No. 3, pp. 2229-2236, July 2018. [doi:10.1109/LRA.2018.2811050]
- 106) Jun Younes Louhi Kasahara, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Fuzzy Clustering of Spatially Relevant Acoustic Data for Defect Detection", *IEEE Robotics and Automation Letters*, Vol. 3, No. 3, pp. 2616-2623, July 2018. [doi:10.1109/LRA.2018.2820178]
- 107) Qi An, Junki Nakagawa, Junko Yasuda, Wen Wen, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "Skill Extraction from Nursing Care Service using Sliding Sheet", *International Journal of Automation Technology*, Vol. 12, No. 4, pp. 533-541, July 2018. [doi:10.20965/ijat.2018.p0533]
- 108) Wen Wen, Rin Minohara, Shunsuke Hamasaki, Takaki Maeda, Qi An, Yusuke Tamura, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "The Readiness Potential Reflects the Reliability of Action Consequence", *Scientific Reports*, Vol. 8, Article number 11865, August 2018. [doi:10.1038/s41598-018-30410-z]
- 109) Akira Shibata, Yukari Okumura, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Refraction-based Bundle Adjustment for Scale Reconstructible Structure from Motion", *Journal of Robotics and Mechatronics*, Vol. 30, No. 4, pp. 660-670, August 2018. [doi:10.20965/jrm.2018.p0660]
- 110) Xiaorui Qiao, Yonghoon Ji, Atsushi Yamashita and Hajime Asama: "Visibility Enhancement for Underwater Robot based on an Improved Underwater Light Model", *Journal of Robotics and Mechatronics*, Vol. 30, No. 5, pp. 781-790, October 2018. [doi:10.20965/jrm.2018.p0781]
- 111) Soichiro Iwataki, Wei Sun, Hiromitsu Fujii, Masataka Fuchida, Alessandro Moro, Takashi Noda, Kazuki Kure, Koichi Nakazawa, Hiroshi Yoshinada, Atsushi Yamashita and Hajime Asama: "Arbitrary Viewpoint Visualization of Pose Change of Bulldozer and Surrounding Dangerous Area", *Transactions of the JSME*, Vol. 84, No. 866, 18-00196, pp. 1-17, October 2018, in Japanese. [doi:10.1299/transjsme.18-00196]
- 112) Tatsuki Nagano, Hiromitsu Fujii, Tatsuya Kittaka, Masataka Fuchida, Yutaro Fukase, Shigeru Aoki, Tomohiro Narumi, Atsushi Yamashita and Hajime Asama: "See-through System Using LiDAR for

- Tele-operated Construction Machines", *Journal of the Japan Society for Precision Engineering*, Vol. 84, No. 12, pp. 1085-1091, December 2018, in Japanese. [doi:10.2493/jjspe.84.1085]
- 113) Hanwool Woo, Yonghoon Ji, Yusuke Tamura, Yasuhide Kuroda, Takashi Sugano, Yasunori Yamamoto, Atsushi Yamashita and Hajime Asama: "Trajectory Prediction of Surrounding Vehicles Considering Individual Driving Characteristics", *International Journal of Automotive Engineering*, Vol. 9, No. 4, pp. 282-288, December 2018. [doi:10.20485/jsaeijae.9.4\_282]
- 114) Yonghoon Ji, Yusuke Tanaka, Yusuke Tamura, Mai Kimura, Atsushi Umemura, Yoshiharu Kaneshima, Hiroki Murakami, Atsushi Yamashita and Hajime Asama: "Adaptive Motion Planning Based on Vehicle Characteristics and Regulations for Off-Road UGVs", *IEEE Transactions on Industrial Informatics*, Vol. 15, No. 1, pp. 599-611, January 2019. [doi:10.1109/TII.2018.2870662]
- 115) Kazunori Yoshida, Qi An, Arito Yozu, Ryosuke Chiba, Kaoru Takakusaki, Hiroshi Yamakawa, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Visual and Vestibular Inputs Affect Muscle Synergies Responsible for Body Extension and Stabilization in Sit-to-Stand Motion", *Frontiers in Neuroscience*, Article 1042, pp. 1-12, January 2019. [doi:10.3389/fnins.2018.01042]
- 116) Qi An, Yuki Ishikawa, Wen Wen, Shu Ishiguro, Koji Ohata, Hiroshi Yamakawa, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Skill Abstraction of Physical Therapist in Hemiplegia Patients Rehabilitation Using A Walking Assist Robot", *International Journal of Automation Technology*, Vol. 13, No. 2, pp. 271-278, March 2019. [doi:10.20965/ijat.2019.p0271]
- 117) Shunsuke Hamasaki, Qi An, Wen Wen, Yusuke Tamura, Hiroshi Yamakawa, Satoshi Unenaka, Satoshi Shibuya, Yukari Ohki, Atsushi Yamashita and Hajime Asama: "Changes in Body Representation of the Human Upper Limb as a Function of Movement and Visual Hand Position", *Journal of Advanced Computational Intelligence and Intelligent Informatics*, Vol. 23, No. 2, pp. 196-208, March 2019. [doi:10.20965/jaciii.2019.p0196]
- 118) Renato Miyagusuku, Atsushi Yamashita and Hajime Asama: "Data Information Fusion from Multiple Access Points for WiFi-based Self-localization", *IEEE Robotics and Automation Letters*, Vol. 4, No. 2, pp. 269-276, April 2019. [doi:10.1109/LRA.2018.2885583]
- 119) Hiroshi Higuchi, Hiromitsu Fujii, Atsushi Taniguchi, Masahiro Watanabe, Atsushi Yamashita and Hajime Asama: "3D Measurement of Large Structure by Multiple Cameras and a Ring Laser", *Journal of Robotics and Mechatronics*, Vol. 31, No. 2, pp. 251-262, April 2019. [doi:10.20965/jrm.2019.p0251]
- 120) Masataka Fuchida, Shota Chikushi, Alessandro Moro, Atsushi Yamashita and Hajime Asama: "Arbitrary Viewpoint Visualization for Teleoperation of Disaster Response Robots", *Journal of Advanced Simulation in Science and Engineering*, Vol. 6, No. 1, pp. 249-259, May 2019. [doi:10.15748/jasse.6.249]
- 121) Junpei Noda, Sarthak Pathak, Hiromitsu Fujii, Atsushi Yamashita, Hajime Asama: "Motion Estimation of Spherical Stereo Camera Considering Confidence of Reconstructed Points", *Journal of the Japan Society for Precision Engineering*, Vol. 85, No. 6, pp. 568-576, June 2019, in Japanese. [doi:10.2493/jjspe.85.568]
- 122) Hiroshi R. Yamasaki, Qi An, Makoto Kinomoto, Koji Takahashi, Takanori Fujii, Hiroki Kogami, Ningjia Yang, Hiroshi Yamakawa, Yusuke Tamura, Matti Itkonen, Moeka Sonoo, Fady S.K. Alnajjar, Atsushi Yamashita, Hironori Otomune, Noriaki Hattori, Hajime Asama, Ichiro Miyai and Shingo Shimoda: "Organization of Functional Modularity in Sitting Balance Response and Gait Performance after Stroke", *Clinical Biomechanics*, Vol. 67, pp. 61-69, July 2019. [doi:10.1016/j.clinbiomech.2019.04.022]
- 123) Xiaorui Qiao, Atsushi Yamashita and Hajime Asama: "Underwater Structure from Motion for Cameras under Refractive Surfaces", *Journal of Robotics and Mechatronics*, Vol. 31, No. 4, pp. 603-611, August 2019. [doi:10.20965/jrm.2019.p0603]
- 124) Jiayu Wu, Hanwool Woo, Yusuke Tamura, Alessandro Moro, Stefano Massaroli, Atsushi Yamashita and Hajime Asama: "Pedestrian Trajectory Prediction Using BiRNN Encoder-Decoder Framework", *Advanced*

- Robotics, Vol. 33, No. 18, pp. 956-969, September 2019. [doi:10.1080/01691864.2019.1635910]
- 125) Hanwool Woo, Yonghoon Ji, Yusuke Tamura, Yasuhide Kuroda, Takashi Sugano, Yasunori Yamamoto, Atsushi Yamashita and Hajime Asama: "Lane-Change Detection Based on Individual Driving Style", *Advanced Robotics*, Vol. 33, No. 20, pp. 1087-1098, October 2019. [doi:10.1080/01691864.2019.1659179]
- 126) Ningjia Yang, Qi An, Hiroki Kogami, Hiroshi Yamakawa, Yusuke Tamura, Kouji Takahashi, Makoto Kinomoto, Hiroshi Yamasaki, Matti Itkonen, Fady Sshibata-Alnajjar, Shingo Shimoda, Noriaki Hattori, Takanori Fujii, Hironori Otomune, Ichiro Miyai, Atsushi Yamashita and Hajime Asama: "Temporal Features of Muscle Synergies in Sit-to-stand Motion Reflect the Motor Impairment of Post-Stroke Patients", *IEEE Transactions on Neural Systems and Rehabilitation Engineering*, Vol. 27, No. 10, pp. 2118-2127, October 2019. [doi:10.1109/TNSRE.2019.2939193]
- 127) Hanwool Woo, Hirokazu Madokoro, Kazuhito Sato, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Advanced Adaptive Cruise Control Based on Operation Characteristic Estimation and Trajectory Prediction", *Applied Sciences*, Vol. 9, No. 22, 4875, pp. 1-18, November 2019. [doi:10.3390/app9224875]
- 128) Soichiro Iwataki, Masataka Fuchida, Alessandro Moro, Takashi Noda, Osamu Yatsuda, Koichi Nakazawa, Hiroshi Yoshinada, Atsushi Yamashita and Hajime Asama: "Sensor Calibration for Arbitrary Viewpoint Visualization System with Laser Radar and Multiple Fisheye Cameras", *Journal of the Japan Society for Precision Engineering*, Vol. 85, No. 12, pp. 1110-1116, December 2019, in Japanese. [doi:10.2493/jjspe.85.1110]
- 129) Ren Komatsu, Hiromitsu Fujii, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Octave Deep Plane-sweeping Network: Reducing Spatial Redundancy for Learning-based Plane-sweeping Stereo", *IEEE Access*, Vol. 7, pp. 150306-150317, December 2019. [doi:10.1109/ACCESS.2019.2947195]
- 130) Satoru Nakamura, Atsushi Yamashita, Fumihiro Inoue, Daisuke Inoue, Yusuke Takahashi, Nobukazu Kamimura and Takao Ueno: "Inspection Test of a Tunnel with the Inspection Vehicle for Tunnel Lining Concrete", *Journal of Robotics and Mechatronics*, Vol. 31, No. 6, pp. 762-771, December 2019. [doi:10.20965/jrm.2019.p0762]
- 131) Yusuke Takahashi, Satoshi Maehara, Hiromitsu Fujii and Atsushi Yamashita: "Detection of Defects Method Using Hammering Robot Imitating Sounds of Workers", *The Journal of the Robotics Society of Japan*, Vol. 38, No. 1, pp. 113-118, January 2020, in Japanese. [doi:10.7210/jrsj.38.113]
- 132) Jun Younes Louhi Kasahara, Atsushi Yamashita and Hajime Asama: "Acoustic Inspection of Concrete Structures Using Active Weak Supervision and Visual Information", *Sensors*, Vol. 20, No. 3, 629, pp. 1-15, January 2020. [doi:10.3390/s20030629]
- 133) Shota Chikushi, Yushi Moriyama, Hiromitsu Fujii, Yusuke Tamura, Hiroshi Yamakawa, Keiji Nagatani, Yuya Sakai, Takumi Chiba, Shingo Yamamoto, Kazuhiro Chayama, Atsushi Yamashita and Hajime Asama: "Automatic Video Presentation for Backhoe Embankment Construction Based on Remote Operator's Requirements", *Journal of the Japan Society for Precision Engineering*, Vol. 86, No. 2, pp. 164-170, February 2020, in Japanese. [doi:10.2493/jjspe.86.164]
- 134) Hanwool Woo, Hirokazu Madokoro, Kazuhito Sato, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Estimation of Operation Characteristics of Following Drivers Based on Car Following Model", *Transactions of Society of Automotive Engineers of Japan*, Vol. 51, No. 2, pp. 304-309, March 2020, in Japanese. [doi:10.11351/jsaeronbun.51.304]
- 135) Dabae Kim, Sarthak Pathak, Alessandro Moro, Atsushi Yamashita and Hajime Asama: "SelfSphNet: Motion Estimation of a Spherical Camera via Self-Supervised Learning", *IEEE Access*, Vol. 8, pp. 41847-41859, March 2020. [doi:10.1109/ACCESS.2020.2977109]
- 136) Ren Komatsu, Hiromitsu Fujii, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Free Viewpoint Image Generation System Using Fisheye Cameras and a Laser Rangefinder for Indoor Robot

- Teleoperation", *ROBOMECH Journal*, Vol. 7, 15, pp. 1-10, March 2020. [doi:10.1186/s40648-020-00163-4]
- 137) Ningjia Yang, Qi An, Hiroki Kogami, Kazunori Yoshida, Hiroshi Yamakawa, Yusuke Tamura, Shingo Shimoda, Hiroshi Yamasaki, Moeka Sonoo, Matti Itkonen, Fady Alnajjar, Noriaki Hattori, Makoto Kinomoto, Kouji Takahashi, Takanori Fujii, Hironori Otomune, Ichiro Miyai, Atsushi Yamashita and Hajime Asama: "Temporal Muscle Synergy Features Estimate Effects of Short-term Rehabilitation in Sit-to-stand of Post-stroke Patients", *IEEE Robotics and Automation Letters*, Vol. 5, No. 2, pp. 1796-1802, April 2020. [doi:10.1109/LRA.2020.2969942]
- 138) Jiaxu Wu, Yusuke Tamura, Yusheng Wang, Hanwool Woo, Alessandro Moro, Atsushi Yamashita and Hajime Asama: "Smartphone Zombie Detection from LiDAR Point Cloud for Mobile Robot Safety", *IEEE Robotics and Automation Letters*, Vol. 5, No. 2, pp. 2256-2263, April 2020. [doi:10.1109/LRA.2020.2970570]
- 139) Veerachart Srisamosorn, Noriaki Kuwahara, Atsushi Yamashita, Taiki Ogata, Shouhei Shirafuji and Jun Ota: "Human Position and Head Direction Tracking in Fisheye Camera Using Randomized Ferns and Fisheye Histograms of Oriented Gradients", *The Visual Computer*, 2020. [doi:10.1007/s00371-019-01749-9]
- 140) Veerachart Srisamosorn, Noriaki Kuwahara, Atsushi Yamashita, Taiki Ogata, Shouhei Shirafuji and Jun Ota: "Indoor Human Face Following with Environmental Fisheye Cameras and Blimp", *Advanced Robotics*, Vol. 34, 2020. [doi:10.1080/01691864.2020.1747537]

### **Referred Conference Papers**

- 1) Jun Sasaki, Gen Nishida, Atsushi Yamashita, Yasumichi Aiyama, Jun Ota and Tamio Arai: "Estimating the Center of Gravity of an Object Using Tilting by Multiple Mobile Robots", *Proceedings of the 1997 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS1997)*, pp. 1748-1753, Grenoble (France), September 1997. [doi:10.1109/IROS.1997.656597]
- 2) Atsushi Yamashita, Jun Sasaki, Jun Ota and Tamio Arai: "Cooperative Manipulation of Objects by Multiple Mobile Robots with Tools", *Proceedings of the 4th Japan-France / 2nd Asia-Europe Congress on Mechatronics (JFM1998)*, pp. 310-315, Kitakyushuu (Japan), October 1998.
- 3) Jun Sasaki, Atsushi Yamashita, Natsuki Miyata, Yasumichi Aiyama, Jun Ota and Tamio Arai: "Constraint of Contacting Points in Cooperative Handling", *Proceedings of the 1998 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS1998)*, pp. 1425-1430, Victoria (Canada), October, 1998. [doi:10.1109/IROS.1998.724789]
- 4) Atsushi Yamashita, Kou Kawano, Jun Ota, Tamio Arai, Masaki Fukuchi, Jun Sasaki and Yasumichi Aiyama: "Planning Method for Cooperative Manipulation by Multiple Mobile Robots using Tools with Motion Errors", *Proceedings of the 1999 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS1999)*, pp. 978-983, Kyongju (Korea), October 1999. [doi:10.1109/IROS.1999.812807]
- 5) Atsushi Yamashita, Masaki Fukuchi, Jun Ota, Tamio Arai and Hajime Asama: "Motion Planning for Cooperative Transportation of a Large Object by Multiple Mobile Robots in a 3D Environment", *Proceedings of the 2000 IEEE International Conference on Robotics and Automation (ICRA2000)*, pp. 3144-3151, San Francisco (U.S.A.), April 2000. [doi:10.1109/ROBOT.2000.845147]
- 6) Atsushi Yamashita, Hajime Asama, Hayato Kaetsu, Isao Endo and Tamio Arai: "Development of Omni-Directional and Step-Climbing Mobile Robot", *Proceedings of the 3rd International Conference on Field and Service Robotics (FSR2001)*, pp. 327-332, Espoo (Finland), June 2001.
- 7) Norikazu Tsunekawa, Atsushi Yamashita, Toru Kaneko and Kenjiro T. Miura: "Object Recognition Using Distributions of Edge Information on Gaussian Spheres", *Proceedings of the Joint Symposium between Sister Universities in Mechanical Engineering (JSSUME2002)*, Kyongju (Korea), August 2002.
- 8) Atsushi Yamashita, Jun Ota, Tamio Arai, Keisuke Ichikawa, Kazuhiro Kamata and Hajime Asama:

- "Cooperative Manipulation and Transportation of a Large Object by Multiple Mobile Robots", Proceedings of the Fourth IFAC Symposium on Intelligent Autonomous Vehicles (IAV2001), pp. 400-403, Sapporo (Japan), September 2001.
- 9) Kenjiro T. Miura, Junji Sone, Atsushi Yamashita, Toru Kaneko, Minoru Ueda and Minetada Osano: "Adaptive Refinement for B-spline Subdivision Curves", Proceedings of the Fifth International Conference on Humans and Computers (HC-2002), pp. 57-61, Aizu (Japan), September 2002.
  - 10) Norikazu Tsunekawa, Atsushi Yamashita, Toru Kaneko and Kenjiro T. Miura: "Edge-Based Recognition of Polyhedral Objects using Gaussian Spheres", Proceedings of the 7th Joint International Conference on Advanced Science and Technology (JICAST2002), pp. 507-510, Hamamatsu (Japan), October 2002.
  - 11) Atsushi Yamashita, Shinya Matsushita, Takeshi Sonohara, Toru Kaneko, Kenjiro T. Miura and Suekichi Isogai: "3-D Measurement of Moving Objects with an Active Stereo Camera System", Proceedings of the 7th Joint International Conference on Advanced Science and Technology (JICAST2002), pp. 511-514, Hamamatsu (Japan), October 2002.
  - 12) Masayuki Kuramoto, Atsushi Yamashita, Toru Kaneko and Kenjiro T. Miura: "Removal of Waterdrops in Images by Using Multiple Cameras", Proceedings of IAPR Workshop on Machine Vision Applications (MVA2002), pp. 80-83, Nara (Japan), December 2002.
  - 13) Atsushi Kawarago, Atsushi Yamashita, Toru Kaneko and Kenjiro T. Miura: "Character Recognition of Thick Books Using a Stereo Vision System", Proceedings of IAPR Workshop on Machine Vision Applications (MVA2002), pp. 358-361, Nara (Japan), December 2002.
  - 14) Atsushi Yamashita, Toru Kaneko, Shinya Matsushita and Kenjiro T. Miura: "Region Extraction with Chromakey Using Striped Backgrounds", Proceedings of IAPR Workshop on Machine Vision Applications (MVA2002), pp. 455-458, Nara (Japan), December 2002.
  - 15) Kenjiro T. Miura, Masashi Adachi, Tsuneo Ikedo, Atsushi Yamashita and Toru Kaneko: "View-Dependent Refinement by Two-Stepped Catmull-Clark Subdivision", Proceedings of the 6th International Conference on Humans and Computers (HC-2003), pp. 30-35, Aizu-Wakamatsu (Japan), August 2003.
  - 16) Kenjiro T. Miura, Junji Sone, Hiroshi Masuda, Atsushi Yamashita and Toru Kaneko : "An Octree-based Approach to Fast Reconstruction of 3D Objects with Radial Basis Functions", Proceedings of the 6th International Conference on Humans and Computers (HC-2003), pp. 36-41, Aizu-Wakamatsu (Japan), August 2003.
  - 17) Atsushi Yamashita, Toru Kaneko, Masaki Nishimura and Kenjiro T. Miura: "Removal of View-Disturbing Waterdrops in Images Using a Pan-Tilt Camera", Proceedings of the 6th International Conference on Humans and Computers (HC-2003), pp. 76-81, Aizu-Wakamatsu (Japan), August 2003.
  - 18) Atsushi Yamashita, Akihisa Nishimoto, Toru Kaneko and Kenjiro T. Miura: "Automatic Generation of Stereogram by Using Stripe Backgrounds", Proceedings of the 6th International Conference on Humans and Computers (HC-2003), pp. 253-258, Aizu-Wakamatsu (Japan), August 2003.
  - 19) Kazutoshi Fujita, Atsushi Yamashita, Toru Kaneko, Hitotaka Asakura, Kenjiro T. Miura and Hajime Asama: "Navigation Planning of Autonomous Mobile Robots with Multiple Observation Strategies", Proceedings of the 6th Japan-France Congress on Mechatronics and 4th Asia-Europe Congress on Mechatronics, pp. 489-494, Saitama (Japan), September 2003.
  - 20) Shingo Kinashi, Hiroyuki Kitazawa, Kenjiro T. Miura, Atsushi Yamashita and Toru Kaneko: "Development of a Geometric-Modeling Device with Force-Feedback", Proceedings of the 6th Japan-France Congress on Mechatronics and 4th Asia-Europe Congress on Mechatronics, pp. 591-596, Saitama (Japan), September 2003.
  - 21) Takahiro Hara, Atsushi Yamashita, Toru Kaneko and Kenjiro T. Miura: "Hammering Test with Image and Sound Signal Processing", Proceedings of the 6th Japan-France Congress on Mechatronics and 4th

Asia-Europe Congress on Mechatronics, pp. 603-608, Saitama (Japan), September 2003.

- 22) Atsushi Yamashita, Etsukazu Hayashimoto, Toru Kaneko and Yoshimasa Kawata: "3-D Measurement of Objects in a Cylindrical Glass Water Tank with a Laser Range Finder", Proceedings of the 2003 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2003), pp. 1578-1583, Las Vegas (USA), October 2003. [doi:10.1109/IROS.2003.1248869]
- 23) Atsushi Yamashita, Masayuki Kuramoto, Toru Kaneko and Kenjiro T. Miura: "A Virtual Wiper -Restoration of Deteriorated Images by Using Multiple Cameras-", Proceedings of the 2003 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2003), pp. 3126-3131, Las Vegas (USA), October 2003. [doi:10.1109/IROS.2003.1249637]
- 24) Atsushi Yamashita, Hirokazu Higuchi, Toru Kaneko and Yoshimasa Kawata: "Three Dimensional Measurement of Object's Surface in Water Using the Light Stripe Projection Method", Proceedings of the 2004 IEEE International Conference on Robotics and Automation (ICRA2004), pp. 2736-2741, New Orleans (USA), April 2004. [doi:10.1109/ROBOT.2004.1307474]
- 25) Atsushi Yamashita, Toru Kaneko and Kenjiro T. Miura: "A Virtual Wiper -Restoration of Deteriorated Images by Using a Pan-Tilt Camera-", Proceedings of the 2004 IEEE International Conference on Robotics and Automation (ICRA2004), pp. 4724-4729, New Orleans (USA), April 2004. [doi:10.1109/ROBOT.2004.1302464]
- 26) Atsushi Yamashita, Atsushi Kawarago, Toru Kaneko and Kenjiro T. Miura: "Shape Reconstruction and Image Restoration for Non-Flat Surfaces of Documents with a Stereo Vision System", Proceedings of the 17th International Conference on Pattern Recognition (ICPR2004), Vol. 1, pp. 482-485, Cambridge (UK), August 2004. [doi:10.1109/ICPR.2004.1334171]
- 27) Yuu Tanaka, Atsushi Yamashita, Toru Kaneko and Kenjiro T. Miura: "Removal of Waterdrops on a Protection Glass Surface from Parallel Stereo Images", Proceedings of the Joint Symposium between Sister Universities in Mechanical Engineering (JSSUME2004), pp. 103-106, Yokohama (Japan), August 2004.
- 28) Hirotaka Asakura, Atsushi Yamashita and Toru Kaneko: "3-D Measurement of an Object by a Mobile Robot Equipped with a Laser Range Finder", Proceedings of the Joint Symposium between Sister Universities in Mechanical Engineering (JSSUME2004), pp. 107-110, Yokohama (Japan), August 2004.
- 29) Shinsuke Ikeda, Atsushi Yamashita and Toru Kaneko: "3-D Shape Reconstruction of Objects in Water by a Laser Range Finder Held on a Manipulator", Proceedings of the Joint Symposium between Sister Universities in Mechanical Engineering (JSSUME2004), pp. 111-114, Yokohama (Japan), August 2004.
- 30) Atsushi Yamashita, Tomoaki Harada, Toru Kaneko and Kenjiro T. Miura: "Removal of Adherent Noises from Images of Dynamic Scenes by Using a Pan-Tilt Camera", Proceedings of the 2004 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2004), pp. 437-442, Sendai (Japan), September 2004. [doi:10.1109/IROS.2004.1389391]
- 31) Atsushi Yamashita, Kazutoshi Fujita, Toru Kaneko and Hajime Asama: "Path and Viewpoint Planning of Mobile Robots with Multiple Observation Strategies", Proceedings of the 2004 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2004), pp. 3195-3200, Sendai (Japan), October 2004. [doi:10.1109/IROS.2004.1389909]
- 32) Yuu Tanaka, Atsushi Yamashita, Toru Kaneko and Kenjiro T. Miura: "Waterdrop Removal on a Protection Glass Surface in Stereo Images", Proceedings of the 8th Joint International Conference on Advanced Science and Technology (JICAST2004), pp. 137-140, Hangzhou (China), December 2004.
- 33) Atsushi Yamashita, Shinsuke Ikeda and Toru Kaneko: "3-D Measurement of Objects in Unknown Aquatic Environments with a Laser Range Finder", Proceedings of the 2005 IEEE International Conference on Robotics and Automation (ICRA2005), pp. 3923-3928, Barcelona (Spain), April 2005. [doi:10.1109/ROBOT.2005.1570718]



- 34) Yuu Tanaka, Atsushi Yamashita, Toru Kaneko and Kenjiro T. Miura: "Restoration of Images Stained with Waterdrops on a Protection Glass Surface by Using a Stereo Image Pair", Proceedings of IAPR Conference on Machine Vision Applications (MVA2005), pp. 152-155, Tsukuba (Japan), May 2005.
- 35) Atsushi Yamashita, Yuu Tanaka and Toru Kaneko: "Removal of Adherent Waterdrops from Images Acquired with Stereo Camera", Proceedings of the 2005 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2005), pp. 953-958, Edmonton (Canada), August 2005. [doi:10.1109/IROS.2005.1545103]
- 36) Kenjiro T. Miura, Junji Sone, Atsushi Yamashita and Toru Kaneko: "Derivation of a General Formula of Aesthetic Curves", Proceedings of the Eighth International Conference on Humans and Computers (HC2005), pp. 166-171, Aizu-Wakamatsu (Japan), September 2005.
- 37) Susumu Kato, Atsushi Yamashita, Toru Kaneko and Kenjiro T. Miura: "Three-dimensional Sensing in Underwater Environments with a Stereo Camera System", Proceedings of the Eighth International Conference on Humans and Computers (HC2005), pp. 205-210, Tokyo (Japan), September 2005.
- 38) Takumi Nakamoto, Atsushi Yamashita, Toru Kaneko: "3-D Map Generation by a Mobile Robot Equipped with a Laser Range Finder", Proceedings of International Workshop on Advanced Image Technology 2006 (IWAIT2006), pp. 154-159, Okinawa (Japan), January 2006.
- 39) Tomoaki Harada, Atsushi Yamashita and Toru Kaneko: "Environment Observation by Structure from Motion with an Omni-directional Camera", Proceedings of International Workshop on Advanced Image Technology 2006 (IWAIT2006), pp. 169-174, Okinawa (Japan), January 2006.
- 40) Atsushi Yamashita, Susumu Kato and Toru Kaneko: "Robust Sensing against Bubble Noises in Aquatic Environments with a Stereo Vision System", Proceedings of the 2006 IEEE International Conference on Robotics and Automation (ICRA2006), pp. 928-933, Orlando (USA), May 2006. [doi:10.1109/ROBOT.2006.1641828]
- 41) Atsushi Yamashita, Takahiro Hara and Toru Kaneko: "Inspection of Visible and Invisible Features of Objects with Image and Sound Signal Processing", Proceedings of the 2006 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2006), pp. 3837-3842, Beijing (China), October 2006. [doi:10.1109/IROS.2006.281790]
- 42) Hiroki Agata, Atsushi Yamashita and Toru Kaneko: "Region Extraction Using Chroma Key with a Checker Pattern Background", Proceedings of the 2nd Asia International Symposium on Mechatronics (AISM2006), B3-06, pp. 1-6, Hong Kong (China), December 2006.
- 43) Atsushi Yamashita, Megumi Fujii and Toru Kaneko: "Color Registration of Underwater Images for Underwater Sensing with Consideration of Light Attenuation", Proceedings of the 2007 IEEE International Conference on Robotics and Automation (ICRA2007), pp. 4570-4575, Rome (Italy), April 2007. [doi:10.1109/ROBOT.2007.364183]
- 44) Yusuke Suzuki, Atsushi Yamashita and Toru Kaneko: "Correction of Geometric and Photometric Distortion of Document Images Using a Stereo Camera System", Proceedings of IAPR Conference on Machine Vision Applications (MVA2007), pp. 215-218, Tokyo (Japan), May 2007.
- 45) Masahiko Onosato, Satoshi Tadokoro, Hiroaki Nakanishi, Kenzo Nonami, Hiroyuki Kawabata, Yasushi Hada, Hajime Asama, Fumiaki Takemura, Kiyoshi Maeda, Kenichiro Miura and Atsushi Yamashita: "Disaster Information Gathering by Aerial Robot Systems", IROS2007 Workshop on Rescue Robotics (MW-3) - DDT Project on Urban Search and Rescue, pp. 23-44, San Diego (USA), October 2007.
- 46) Toru Tsuchiya, Atsushi Yamashita, Toru Kaneko, Yasuhiro Kaneko and Hirokatsu Muramatsu: "Scheduling Optimization of Component Mounting in Printed Circuit Board Assembly by Prioritizing Simultaneous Pickup", Proceedings of the 2007 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2007), pp. 2913-2918, San Diego (USA), November 2007. [doi:10.1109/IROS.2007.4399002]
- 47) Atsushi Yamashita, Akira Fujii and Toru Kaneko: "Three Dimensional Measurement of Objects in Liquid

- and Estimation of Refractive Index of Liquid by Using Images of Water Surface with a Stereo Vision System", Proceedings of the 2008 IEEE International Conference on Robotics and Automation (ICRA2008), pp. 974-979, Pasadena (USA), May 2008. [doi:10.1109/ROBOT.2008.4543331]
- 48) Atsushi Yamashita, Isao Fukuchi, Toru Kaneko and Kenjiro T. Miura: "Removal of Adherent Noises from Image Sequences by Spatio-Temporal Image Processing", Proceedings of the 2008 IEEE International Conference on Robotics and Automation (ICRA2008), pp. 2386-2391, Pasadena (USA), May 2008. [doi:10.1109/ROBOT.2008.4543570]
  - 49) Yu Ito, Atsushi Yamashita and Toru Kaneko: "A Multi-Viewpoint Human Tracking Based on Face Detection Using Haar-like Features and a Mean-Shift Tracker", Proceedings of the 3rd Asia International Symposium on Mechatronics (AISM2008), TA1-1(2), pp. 1-4, Sapporo (Japan), August 2008.
  - 50) Shinya Iwashina, Atsushi Yamashita and Toru Kaneko: "3-D Map Building in Dynamic Environments by a Mobile Robot Equipped with two Laser Range Finders", Proceedings of the 3rd Asia International Symposium on Mechatronics (AISM2008), Sapporo (Japan), TP1-3(1), pp. 1-5, August 2008.
  - 51) Ryosuke Kawanishi, Atsushi Yamashita and Toru Kaneko: "Construction of 3D Environment Model from an Omni-Directional Image Sequence", Proceedings of the 3rd Asia International Symposium on Mechatronics (AISM2008), TP1-3(2), pp. 1-6, Sapporo (Japan), August 2008. (AISM2008 Best Student Paper Award)
  - 52) Toru Tsuchiya, Atsushi Yamashita, Toru Kaneko, Yasuhiro Kaneko and Hirokatsu Muramatsu: "Scheduling and Feeder Arrangement for Simultaneous Pickup in Printed Circuit Board Assembly of Placement Machines", Proceedings of the 3rd Asia International Symposium on Mechatronics (AISM2008), TP2-1(3), pp. 1-6, Sapporo (Japan), August 2008.
  - 53) Atsushi Yamashita, Hiroki Agata and Toru Kaneko: "Every Color Chromakey", Proceedings of the 19th International Conference on Pattern Recognition (ICPR2008), pp. 1-4, TuBCT9.40, Tampa (USA), December 2008. [doi:10.1109/ICPR.2008.4761643]
  - 54) Ryohei Kawai, Atsushi Yamashita and Toru Kaneko: "Three-Dimensional Measurement of Objects in Water by Using Space Encoding Method", Proceedings of the 2009 IEEE International Conference on Robotics and Automation (ICRA2009), pp. 2830-2835, Kobe (Japan), May 2009. [doi:10.1109/ROBOT.2009.5152430]
  - 55) Ryosuke Kawanishi, Atsushi Yamashita and Toru Kaneko: "Estimation of Camera Motion with Feature Flow Model for 3D Environment Modeling by Using Omni-Directional Camera", Proceedings of the 2009 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2009), pp. 3089-3094, St. Louis (USA), October 2009. (IEEE Robotics and Automation Society Japan Chapter Young Award) [doi:10.1109/IROS.2009.5354671]
  - 56) Atsushi Yamashita, Isao Fukuchi and Toru Kaneko: "Noises Removal from Image Sequences Acquired with Moving Camera by Estimating Camera Motion from Spatio-Temporal Information", Proceedings of the 2009 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2009), pp. 3794-3801, St. Louis (USA), October 2009. [doi:10.1109/IROS.2009.5354639]
  - 57) Kenki Matsui, Atsushi Yamashita and Toru Kaneko: "3-D Shape Reconstruction of Pipe with Omni-Directional Laser and Omni-Directional Camera", Proceedings of the 3rd International Conference of Asian Society for Precision Engineering and Nanotechnology (ASPEN2009), 1A2-15, pp. 1-5, Kokura (Japan), November 2009.
  - 58) Ryohei Kawai, Atsushi Yamashita and Toru Kaneko: "Shape Measurement of Underwater Objects by Using Space Encoding Method", Proceedings of the 3rd International Conference of Asian Society for Precision Engineering and Nanotechnology (ASPEN2009), 1A2-16, pp. 1-5, Kokura (Japan), November 2009.
  - 59) Ryosuke Kawanishi, Atsushi Yamashita and Toru Kaneko: "Environment Measurement based on Structure from Motion with Feature Flow Model by Using Omni-Directional Camera", Proceedings of the 3rd International Conference of Asian Society for Precision Engineering and Nanotechnology (ASPEN2009),

2A2-7, pp. 1-5, Kokura (Japan), November 2009.

- 60) Akiyoshi Matsui, Atsushi Yamashita and Toru Kaneko: "Blurred Wire Netting Removal from an Image Using Multiple Focusing", Proceedings of the 12th International Conference on Humans and Computers (HC-2009), pp. 80-85, Hamamatsu (Japan), December 2009.
- 61) Kenki Matsui, Atsushi Yamashita and Toru Kaneko: "3-D Shape Measurement of Pipe by Range Finder Constructed with Omni-Directional Laser and Omni-Directional Camera", Proceedings of the 2010 IEEE International Conference on Robotics and Automation (ICRA2010), pp. 2537-2542, Anchorage (USA), May 2010. [doi:10.1109/ROBOT.2010.5509851]
- 62) Atsushi Yamashita, Akiyoshi Matsui and Toru Kaneko: "Fence Removal from Multi-Focus Images", Proceedings of the 20th International Conference on Pattern Recognition (ICPR2010), pp. 4532-4535, Istanbul (Turkey), August 2010. [doi:10.1109/ICPR.2010.1101]
- 63) Atsushi Yamashita, Shinya Iwashina and Toru Kaneko: "View Planning and 3D Map Building by a Mobile Robot Equipped with two Range Sensors", Proceedings of the 2010 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2010), pp. 1545, Taipei (Taiwan), October 2010.
- 64) Atsushi Yamashita, Yudai Shirane and Toru Kaneko: "Monocular Underwater Stereo -3D Measurement Using Difference of Appearance Depending on Optical Paths-", Proceedings of the 2010 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2010), pp. 3652-3657, Taipei (Taiwan), October 2010. [doi:10.1109/IROS.2010.5649444]
- 65) Atsushi Yamashita, Rie Miyaki and Toru Kaneko: "Color Information Presentation for Color Vision Defective by Using a Projector Camera System", Proceedings of the ACCV2010 Workshop on Application of Computer Vision for Mixed and Augmented Reality, Queenstown (New Zealand), November 2010. [doi:10.1007/978-3-642-22819-3\_10]
- 66) Masaaki Kitaoka, Atsushi Yamashita and Toru Kaneko: "Obstacle Avoidance and Path Planning Using Color Information for a Biped Robot Equipped with a Stereo Camera System", Proceedings of the 4th Asia International Symposium on Mechatronics (AISM2010), pp. 38-43, Singapore (Singapore), December 2010. (AISM2010 Best Paper Award)
- 67) Atsushi Yamashita, So Kuno and Toru Kaneko: "Assisting System of Visually Impaired in Touch Panel Operation Using Stereo Camera", Proceedings of the 2011 IEEE International Conference on Image Processing (ICIP2011), pp. 1001-1004, Brussels (Belgium), September 2011. [doi:10.1109/ICIP.2011.6116728]
- 68) Daisuke Ishizuka, Atsushi Yamashita, Ryosuke Kawanishi, Toru Kaneko and Hajime Asama: "Self-localization of Mobile Robot Equipped with Omnidirectional Camera Using Image Matching and 3D-2D Edge Matching", Proceedings of the 2011 IEEE International Conference on Computer Vision Workshop (Proceedings of the 11th Workshop on Omnidirectional Vision, Camera Networks and Non-classical Cameras (OMNIVIS2011)), pp. 272-279, Barcelona (Spain), November 2011. [doi:10.1109/ICCVW.2011.6130253]
- 69) Shinichi Goto, Atsushi Yamashita, Ryosuke Kawanishi, Toru Kaneko and Hajime Asama: "3D Environment Measurement Using Binocular Stereo and Motion Stereo by Mobile Robot with Omnidirectional Stereo Camera", Proceedings of the 2011 IEEE International Conference on Computer Vision Workshop (Proceedings of the 11th Workshop on Omnidirectional Vision, Camera Networks and Non-classical Cameras (OMNIVIS2011)), pp. 296-303, Barcelona (Spain), November 2011. [doi:10.1109/ICCVW.2011.6130256]
- 70) Atsushi Yamashita, Ryosuke Kawanishi, Tadashi Koketsu, Toru Kaneko and Hajime Asama: "Underwater Sensing with Omni-Directional Stereo Camera", Proceedings of the 2011 IEEE International Conference on Computer Vision Workshop (Proceedings of the 11th Workshop on Omnidirectional Vision, Camera

Networks and Non-classical Cameras (OMNIVIS2011)), pp. 304-311, Barcelona (Spain), November 2011. [doi:10.1109/ICCVW.2011.6130257]

- 71) Atsushi Yamashita, Kenki Matsui, Ryosuke Kawanishi, Toru Kaneko, Taro Murakami, Hayato Omori, Taro Nakamura and Hajime Asama: "Self-Localization and 3-D Model Construction of Pipe by Earthworm Robot Equipped with Omni-Directional Rangefinder", Proceedings of the 2011 IEEE International Conference on Robotics and Biomimetics (ROBIO2011), pp. 1017-1023, Phuket Island (Thailand), December 2011. [doi:10.1109/ROBIO.2011.6181421]
- 72) Gakuto Masuyama, Atsushi Yamashita and Hajime Asama: "Robot Motion Planning Utilizing Local Propagation of Information Based on Particle Swarm and Its Internal Parameters", Proceedings of the 2011 IEEE International Conference on Robotics and Biomimetics (ROBIO2011), pp. 1053-1058, Phuket Island (Thailand), December 2011.
- 73) Shunsuke Hamasaki, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Prediction of Human's Movement for Collision Avoidance of Mobile Robot", Proceedings of the 2011 IEEE International Conference on Robotics and Biomimetics (ROBIO2011), pp. 1633-1638, Phuket Island (Thailand), December 2011.
- 74) Atsushi Yamashita, Yu Ito, Toru Kaneko and Hajime Asama: "Human Tracking with Multiple Cameras Based on Face Detection and Mean Shift", Proceedings of the 2011 IEEE International Conference on Robotics and Biomimetics (ROBIO2011), pp. 1664-1671, Phuket Island (Thailand), December 2011.
- 75) Takahito Shimizu, Masashi Awai, Atsushi Yamashita and Toru Kaneko: "Mobile Robot System Realizing Human Following and Autonomous Returning Using Laser Range Finder and Camera", Proceedings of the 18th Korea-Japan Joint Workshop on Frontiers of Computer Vision (FCV2012), pp. 97-102, Kawasaki (Japan), February 2012.
- 76) Ryosuke Kawanishi, Atsushi Yamashita, Toru Kaneko and Hajime Asama: "Line-based Camera Movement Estimation by Using Parallel Lines in Omnidirectional Video", Proceedings of the 2012 IEEE International Conference on Robotics and Automation (ICRA2012), pp. 3573-3579, Saint Paul (USA), May 2012. [doi:10.1109/ICRA.2012.6224816]
- 77) Atsushi Yamashita, Fumiya Tsurumi, Toru Kaneko and Hajime Asama: "Automatic Removal of Foreground Occluder From Multi-Focus Images", Proceedings of the 2012 IEEE International Conference on Robotics and Automation (ICRA2012), pp. 5410-5416, Saint Paul (USA), May 2012. [doi:10.1109/ICRA.2012.6224549]
- 78) Guanghui Li, Yusuke Tamura, Min Wu, Atsushi Yamashita and Hajime Asama: "Hybrid Dynamic Mobile Task Allocation and Reallocation Methodology for Distributed Multi-robot Coordination", Proceedings of the 2012 IEEE/ASME International Conference on Advanced Intelligent Mechatronics (AIM2012), KaoHsiung (Taiwan), pp. 190-195, July 2012.
- 79) Guanghui Li, Atsushi Yamashita, Hajime Asama and Yusuke Tamura: "An Efficient Improved Artificial Potential Field Based Regression Search Method for Robot Path Planning", Proceedings of the 2012 IEEE International Conference on Mechatronics and Automation (ICMA2012), pp. 1227-1232, Sichuan (China), August 2012.
- 80) Qi An, Yuki Ishikawa, Junki Nakagawa, Atsushi Kuroda, Hiroyuki Oka, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "Evaluation of Wearable Gyroscope and Accelerometer Sensor (PocketIMU2) during Walking and Sit-to-Stand Motions", Proceedings of the 21st IEEE International Symposium on Robot and Human Interactive Communication (Ro-Man2012), pp. 731-736, Paris (France), September 2012.
- 81) Tatsuya Naruse, Toru Kaneko, Atsushi Yamashita and Hajime Asama: "3-D Measurement of Objects in Water Using Fish-eye Stereo Camera", Proceedings of the 2012 IEEE International Conference on Image

- Processing (ICIP2012), pp. 2773-2776, Orlando (USA), October 2012. [doi:10.1109/ICIP.2012.6467474]
- 82) Yusuke Tamura, Phuoc Dai Le, Kentarou Hitomi, Naiwala P. Chandrasiri, Takashi Bando, Atsushi Yamashita and Hajime Asama: "Development of Pedestrian Behavior Model Taking Account of Intention", Proceedings of the 2012 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2012), pp. 382-387, Vilamoura (Portugal), October 2012. [doi:10.1109/IROS.2012.6385599]
- 83) Gakuto Masuyama, Atsushi Yamashita and Hajime Asama: "Intrinsically Motivated Anticipatory Learning Utilizing Transformation Invariance", Proceedings of the IEEE Conference on Development and Learning / EpiRob 2012 (ICDL-EpiRob2012), San Diego (USA), November 2012.
- 84) Kazushi Watanabe, Ryosuke Kawanishi, Atsushi Yamashita, Yuichi Kobayashi, Toru Kaneko and Hajime Asama: "Mobile Robot Navigation in Textureless Unknown Environment Based on Plane Estimation by Using Single Omni-directional Camera", Proceedings of the 2012 IEEE/SICE International Symposium on System Integration (SII2012), pp. 37-42, Fukuoka (Japan), December 2012.
- 85) Min Wu, Atsushi Yamashita and Hajime Asama: "Rule Abstraction and Transfer in Reinforcement Learning by Decision Tree", Proceedings of the 2012 IEEE/SICE International Symposium on System Integration (SII2012), pp. 529-534, Fukuoka (Japan), December 2012.
- 86) Hiroto Ibe, Atsushi Yamashita, Toru Kaneko and Yuichi Kobayashi: "3D Measurement of Transparent Vessel and Submerged Object Using Laser Range Finder", Proceedings of the International Workshop on Advanced Image Technology 2013 (IWAIT2013), pp. 78-83, Nagoya (Japan), January 2013.
- 87) Fumiya Tsurumi, Yuichi Kobayashi, Toru Kaneko and Atsushi Yamashita: "Removal of Reflection from Nightscape Parallel Stereo Images of Distant View through Window", Proceedings of the International Workshop on Advanced Image Technology 2013 (IWAIT2013), pp. 626-631, Nagoya (Japan), January 2013.
- 88) Masato Kondo, Atsushi Yamashita, Toru Kaneko and Yuichi Kobayashi: "Control of Mobile Robot Equipped with Stereo Camera Using the Number of Fingers", Proceedings of the International Workshop on Advanced Image Technology 2013 (IWAIT2013), pp. 723-728, Nagoya (Japan), January 2013. (Candidate for Best Paper Award)
- 89) Yoshiki Mori, Atsushi Yamashita, Masayuki Tanaka, Ryuho Kataoka, Yoshizumi Miyoshi, Toru Kaneko, Masatoshi Okutomi and Hajime Asama: "Calibration of Fish-Eye Stereo Camera for Aurora Observation", Proceedings of the International Workshop on Advanced Image Technology 2013 (IWAIT2013), pp. 729-734, Nagoya (Japan), January 2013. (Candidate for Best Paper Award)
- 90) Yutaro Ohshima, Yuichi Kobayashi, Toru Kaneko, Atsushi Yamashita and Hajime Asama: "Meal Support System with Spoon Using Laser Range Finder and Manipulator", Proceedings of the 2013 IEEE Workshop on Robot Vision (WoRV2013), pp. 82-87, Clearwater Beach (USA), January 2013.
- 91) Naoki Ibe, Gakuto Masuyama, Atsushi Yamashita and Hajime Asama: "Humanlike Behavior Model with Probabilistic Intention", Proceedings of ACM SIGGRAPH2013 Posters, Article No. 7, Anaheim (USA), July 2013. [doi:10.1145/2503385.2503393]
- 92) Daiki Kawakami, Kaito Makino, Yuichi Kobayashi, Toru Kaneko, Atsushi Yamashita and Hajime Asama: "Projector Camera System Presenting Color Information for Color Vision Deficiency", Proceedings of the 32nd JSST Annual International Conference on Simulation Technology (JSST2013), Tokyo (Japan), September 2013. (JSST2013 Outstanding Presentation Award)
- 93) Junki Nakagawa, Qi An, Yuki Ishikawa, Hiroyuki Oka, Kaoru Takakusaki, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "Analysis of Joint Correlation between Arm and Lower Body in Dart Throwing Motion", Proceedings of the 2013 IEEE International Conference on Systems, Man, and Cybernetics (SMC2013), pp. 1223-1228, Manchester (UK), October 2013. [doi:10.1109/SMC.2013.212]
- 94) Qi An, Yuki Ishikawa, Junki Nakagawa, Hiroyuki Oka, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "Muscle Synergy Analysis of Human Standing-up Motion with Different Chair Heights and

- Different Motion Speeds", Proceedings of the 2013 IEEE International Conference on Systems, Man, and Cybernetics (SMC2013), pp. 3579-3584, Manchester (UK), October 2013. [doi:10.1109/SMC.2013.610]
- 95) Gakuto Masuyama, Atsushi Yamashita and Hajime Asama: "Selective Exploration Exploiting Skills in Hierarchical Reinforcement Learning Framework", Proceedings of the 2013 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2013), pp. 692-697, Tokyo (Japan), November 2013. [doi:10.1109/IROS.2013.6696426]
- 96) Qi An, Yuki Ishikawa, Junki Nakagawa, Hiroyuki Oka, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "Analysis of Contribution of Muscle Synergies on Sit-to-Stand Motion Using Musculoskeletal Model", Proceedings of the 2013 IEEE Workshop on Advanced Robotics and its Social Impacts (ARSO2013), pp. 13-18, Tokyo (Japan), November 2013.
- 97) Takuma Tsuji, Hiroshi Yamakawa, Atsushi Yamashita, Kaoru Takakusaki, Takaki Maeda, Motoichiro Kato, Hiroyuki Oka and Hajime Asama: "Analysis of Electromyography and Skin Conductance Response During Rubber Hand Illusion", Proceedings of the 2013 IEEE Workshop on Advanced Robotics and its Social Impacts (ARSO2013), pp. 88-93, Tokyo (Japan), November 2013.
- 98) Takaaki Sato, Alessandro Moro, Atsushi Sugahara, Tsuyoshi Tasaki, Atsushi Yamashita and Hajime Asama: "Spatio-Temporal Bird's-Eye View Images Using Multiple Fish-eye Cameras", Proceedings of the 2013 IEEE/SICE International Symposium on System Integration (SII2013), pp. 753-758, Kobe (Japan), December 2013. [doi:10.1109/SII.2013.6776674]
- 99) Yuki Ishikawa, Qi An, Junki Nakagawa, Hiroyuki Oka, Atsushi Yamashita and Hajime Asama: "Effect of Varus Gait on Anterior Cruciate Ligament: To Clarify Mechanism of Pathogenesis of Knee Osteoarthritis", Osteoarthritis and Cartilage, Vol. 22 Supplement (Abstracts from the 2014 World Congress on Osteoarthritis), pp. S113-S114, Paris (France), April 2014.
- 100) Qi An, Yuki Ishikawa, Tetsuro Funato, Shinya Aoi, Hiroyuki Oka, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "Generation of Human Standing-up Motion with Muscle Synergies Using Forward Dynamic Simulation", Proceedings of the 2014 IEEE International Conference on Robotics and Automation (ICRA2014), pp. 730-735, Hong Kong (China), June 2014. [doi:10.1109/ICRA.2014.6906935]
- 101) Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Automated Diagnosis of Material Condition in Hammering Test Using a Boosting Algorithm", Proceedings of the 2014 IEEE Workshop on Advanced Robotics and its Social Impacts (ARSO2014), pp. 101-107, Evanston (USA), September 2014.
- 102) Koshiro Yanai, Qi An, Yuki Ishikawa, Junki Nakagawa, Wen Wen, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "Visualization of Muscle Activity during Squat Motion for Skill Education", Proceedings of the 2nd International Conference on Serviceology (ICServ2014), pp. 86-90, Yokohama (Japan), September 2014.
- 103) Junki Nakagawa, Qi An, Yuki Ishikawa, Koshiro Yanai, Wen Wen, Hiroshi Yamakawa, Junko Yasuda, Atsushi Yamashita and Hajime Asama: "Extraction and Evaluation of Proficiency in Bed Care Motion for Education Service of Nursing Skill", Proceedings of the 2nd International Conference on Serviceology (ICServ2014), pp. 91-96, Yokohama (Japan), September 2014.
- 104) Kazuya Sugimoto, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Half Diminished Reality Image Using Three RGB-D Sensors for Remote Control Robots", Proceedings of the 12th IEEE International Symposium on Safety, Security, and Rescue Robotics (SSRR2014), 43, Toyako (Japan), October 2014. [doi:10.1109/SSRR.2014.7017676]
- 105) Jonghoon Im, Atsushi Yamashita, Hiromitsu Fujii and Hajime Asama: "Correction of Over and Under Exposure Images Using Multiple Lighting System", Proceedings of the 2nd International Conference on Maintenance Science and Technology (ICMST2014), pp. 125-126, Kobe (Japan), November 2014.
- 106) Hiromitsu Fujii, Takayuki Kubo, Atsushi Yamashita, Akira Takeuchi, Masayuki Tanaka, Ryuho

- Kataoka, Yoshizumi Miyoshi, Masatoshi Okutomi and Hajime Asama: "Aurora 3D-Measurement and Visualization Using Fish-Eye Stereo Camera", Proceedings of ACM SIGGRAPH Asia 2014 Posters, Article No. 24, Shenzhen (China), December 2014. [doi:10.1145/2668975.2669011]
- 107) Veerachart Srisamosorn, Noriaki Kuwahara, Atsushi Yamashita, Taiki Ogata and Jun Ota: "Automatic Face Tracking System using Quadrotors: Control by Goal Position Thresholding", Proceedings of the 2014 IEEE International Conference on Robotics and Biomimetics (ROBIO2014), pp. 1314-1319, Bali (Indonesia), December 2014.
- 108) Jonghoon Im, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Compensation of Over and Under Exposure Image Using Multiple Light Switching", Proceedings of the 2014 IEEE/SICE International Symposium on System Integration (SII2014), pp. 147-152, Tokyo (Japan), December 2014.
- 109) Kazuki Sakamoto, Alessandro Moro, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Three-Dimensional Measurement of Objects in Liquid with an Unknown Refractive Index Using Fisheye Stereo Camera", Proceedings of the 2014 IEEE/SICE International Symposium on System Integration (SII2014), pp. 281-286, Tokyo (Japan), December 2014.
- 110) Satoshi Ishikawa, Yuichi Kobayashi, Toru Kaneko, Susumu Ishihara and Atsushi Yamashita: "A Study on Image Generation with Shifted Perspective Using Two In-vehicle Camera Images", Proceedings of the 2015 Joint Conference of the International Workshop on Advanced Image Technology (IWAIT) and the International Forum on Medical Imaging in Asia (IFMIA), Paper No. 461, pp. 1-3, Tainan (Taiwan), January 2015.
- 111) Naoki Ibe, Atsushi Yamashita and Hajime Asama: "Flexible Marker-based Augmented Reality Based on Estimation of Object Pose", Proceedings of the 2015 Joint Conference of the International Workshop on Advanced Image Technology (IWAIT) and the International Forum on Medical Imaging in Asia (IFMIA), Paper No. 111, pp. 1-4, Tainan (Taiwan), January 2015.
- 112) Yusuke Tanaka, Yonghoon Ji, Atsushi Yamashita and Hajime Asama: "Fuzzy Based Traversability Analysis for a Mobile Robot on Rough Terrain", Proceedings of the 2015 IEEE International Conference on Robotics and Automation (ICRA2015), pp. 3965-3970, Seattle (USA), May 2015. [doi:10.1109/ICRA.2015.7139753]
- 113) Akira Shibata, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Scale-Reconstructable Structure from Motion Using Refraction with a Single Camera", Proceedings of the 2015 IEEE International Conference on Robotics and Automation (ICRA2015), pp. 5239-5244, Seattle (USA), May 2015. (IEEE Robotics and Automation Society Japan Chapter Young Award) [doi:10.1109/ICRA.2015.7139929]
- 114) Qi An, Yuki Ishikawa, Shinya Aoi, Tetsuro Funato, Hiroyuki Oka, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "Analysis of Muscle Synergy Contribution on Human Standing-up Motion Using Human Neuro-Musculoskeletal Model", Proceedings of the 2015 IEEE International Conference on Robotics and Automation (ICRA2015), pp. 5885-5890, Seattle (USA), May 2015. [doi:10.1109/ICRA.2015.7140023]
- 115) Seungchul Kwak, Yonghoon Ji, Atsushi Yamashita and Hajime Asama: "Development of Acoustic Camera-Imaging Simulator Based on Novel Model", Proceedings of the 2015 IEEE 15th International Conference on Environment and Electrical Engineering (EEEIC2015), pp. 1719-1724, Rome (Italy), June 2015. [doi:10.1109/EEEIC.2015.7165431]
- 116) Xiaorui Qiao, Junki Nakagawa, Koshiro Yanai, Junko Yasuda, Wen Wen, Atsushi Yamashita and Hajime Asama: "Nurse Bed Care Activity Analysis for Intelligent Training Service", Proceedings of the 3rd International Conference on Serviceology (ICServ2015), T2-1-2, pp. 1-6, San Jose (USA), July 2015.
- 117) Hiroyuki Okamoto, Alessandro Moro, Atsushi Yamashita and Hajime Asama: "Toward Sports Training Service with the Interactive Learning Platform", Proceedings of the 3rd International Conference on

Serviceology (ICServ2015), T2-1-3, pp. 1-4, San Jose (USA), July 2015.

- 118) Wen Wen, Xiaorui Qiao, Koshiro Yanai, Junki Nakagawa, Junko Yasuda, Atsushi Yamashita and Hajime Asama: "Skill Evaluation and Education Services for Bed-Care Nursing with Sliding Sheet with Regression Analysis", Proceedings of the 3rd International Conference on Serviceology (ICServ2015), T3-1-2, pp. 1-5, San Jose (USA), July 2015.
- 119) Guanghui Li, Shuiguang Tong, Yang Li, Feiyun Cong, Zheming Tong, Atsushi Yamashita and Hajime Asama: "Hybrid Dynamical Moving Task Allocation Methodology for Distributed Multi-robot Coordination System", Proceedings of the 2015 IEEE International Conference on Mechatronics and Automation (ICMA2015), pp. 1412-1417, Beijing (China), August 2015.
- 120) Yonghoon Ji, Atsushi Yamashita and Hajime Asama: "Automatic Calibration and Trajectory Reconstruction of Mobile Robot in Camera Sensor Network", Proceedings of the 11th Annual IEEE International Conference on Automation Science and Engineering (CASE2015), pp. 206-211, Gothenburg (Sweden), August 2015. [doi:10.1109/CoASE.2015.7294063]
- 121) Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Improvement of Environmental Adaptivity of Defect Detector for Hammering Test Using Boosting Algorithm", Proceedings of the 2015 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2015), pp. 6507-6514, Hamburg (Germany), October 2015. [doi:10.1109/IROS.2015.7354307]
- 122) Renato Miyagusuku, Atsushi Yamashita and Hajime Asama: "Gaussian Processes with Input-dependent Noise Variance for Wireless Signal Strength-based Localization", Proceedings of the 13th IEEE International Symposium on Safety, Security, and Rescue Robotics (SSRR2015), West Lafayette (USA), October 2015. [doi:10.1109/SSRR.2015.7442993]
- 123) Guanghui Li, Shuiguang Tong, Gang Lv, Renyuan Xiao, Feiyun Cong, Zheming Tong, Atsushi Yamashita and Hajime Asama: "An Improved Artificial Potential Field-based Simultaneous Forward Search (Improved APF-based SIFORS) method for Robot Path Planning", Proceedings of the 12th International Conference on Ubiquitous Robots and Ambient Intelligence (URAI2015), Goyang (Korea), October 2015.
- 124) Akira Takeuchi, Hiromitsu Fujii, Atsushi Yamashita, Masayuki Tanaka, Ryuho Kataoka, Yoshizumi Miyoshi, Masatoshi Okutomi and Hajime Asama: "3D Visualization of Aurora from Optional Viewpoint at Optional Time", Proceedings of ACM SIGGRAPH Asia 2015 Posters, Article No. 9, Kobe (Japan), November 2015. [doi:10.1145/2820926.2820967]
- 125) Daisuke Tomoi, Wen Wen, Hiroshi Yamakawa, Shunsuke Hamasaki, Kaoru Takakusaki, Qi An, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Estimation of Stress During Car Race with Factor Analysis", Proceedings of the 2015 International Symposium on Micro-Nano Mechatronics and Human Science (MHS2015), pp. 213-216, Nagoya (Japan), November 2015.
- 126) Shunsuke Hamasaki, Qi An, Wen Wen, Yusuke Tamura, Hiroshi Yamakawa, Atsushi Yamashita, Hajime Asama, Satoshi Shibuya and Yukari Ohki: "Evaluating Effect of Sense of Ownership and Sense of Agency on Body Representation Change of Human Upper Limb", Proceedings of the 2015 International Symposium on Micro-Nano Mechatronics and Human Science (MHS2015), pp. 254-257, Nagoya (Japan), November 2015. (Best Poster Award)
- 127) Tatsuya Kittaka, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Seeing through Obstacles by Using Movable RGB-D Sensors", Proceedings of the 6th International Conference on Advanced Mechatronics (ICAM2015), pp. 29-30, Tokyo (Japan), December 2015. (ICAM2015 Honorable Mention)
- 128) Binbin Xu, Sarthak Pathak, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Robot Body Occlusion Removal in Omnidirectional Video Using Color and Shape Information", Proceedings of the 6th International Conference on Advanced Mechatronics (ICAM2015), pp. 49-50, Tokyo (Japan), December



2015. (ICAM2015 Honorable Mention)

- 129) Sarthak Pathak, Alessandro Moro, Atsushi Yamashita and Hajime Asama: "Rotation Removed Stabilization of Omnidirectional Videos Using Optical Flow", Proceedings of the 6th International Conference on Advanced Mechatronics (ICAM2015), pp. 51-52, Tokyo (Japan), December 2015.
- 130) Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Boosting-based Visualization of Concrete Defects for Hammering Inspection", Proceedings of the 6th International Conference on Advanced Mechatronics (ICAM2015), p. 55, Tokyo (Japan), December 2015. (ICAM2015 Best Paper)
- 131) Qi An, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "Muscle Synergies of Sit-to-Stand and Walking Account for Sit-to-Walk Motion", Proceedings of the 6th International Conference on Advanced Mechatronics (ICAM2015), pp. 96-97, Tokyo (Japan), December 2015. (ICAM2015 Honorable Mention)
- 132) Yonghoon Ji, Atsushi Yamashita and Hajime Asama: "Automatic Camera Pose Estimation Based on Textured 3D Map Information", Proceedings of the 6th International Conference on Advanced Mechatronics (ICAM2015), pp. 100-101, Tokyo (Japan), December 2015. (ICAM2015 Honorable Mention)
- 133) Ren Komatsu, Hiromitsu Fujii, Hitoshi Kono, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Bird's-eye View Image Generation with Camera Malfunction in Irradiation Environment", Proceedings of the 6th International Conference on Advanced Mechatronics (ICAM2015), pp. 177-178, Tokyo (Japan), December 2015.
- 134) Seungchul Kwak, Yonghoon Ji, Atsushi Yamashita and Hajime Asama: "3-D Reconstruction of Underwater Object: Analytical System for Extracting Feature Points Using Two Different Acoustic Views", Proceedings of the 6th International Conference on Advanced Mechatronics (ICAM2015), pp. 197-198, Tokyo (Japan), December 2015.
- 135) Hiroshi Higuchi, Hiromitsu Fujii, Atsushi Taniguchi, Masahiro Watanabe, Atsushi Yamashita and Hajime Asama: "3D Measurement of Large Structures with a Ring Laser and a Camera Using Structure from Motion for Integrating Cross Sections", Proceedings of the 6th International Conference on Advanced Mechatronics (ICAM2015), pp. 233-234, Tokyo (Japan), December 2015.
- 136) Hitoshi Kono, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Distributed Cooperative Fault Diagnosis for Internal Electrical Components of Robot System", Proceedings of the 6th International Conference on Advanced Mechatronics (ICAM2015), pp. 235-236, Tokyo (Japan), December 2015.
- 137) Yusuke Tanaka, Yonghoon Ji, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Course Detection from Integrated 3D Environment Measurement by Multiple Mobile Robots", Proceedings of the 6th International Conference on Advanced Mechatronics (ICAM2015), pp. 237-238, Tokyo (Japan), December 2015.
- 138) Hanwool Woo, Yonghoon Ji, Hitoshi Kono, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Detection Method of Lane Change Intentions in Other Drivers Using Hidden Markov Models", Proceedings of the 6th International Conference on Advanced Mechatronics (ICAM2015), pp. 253-254, Tokyo (Japan), December 2015.
- 139) Renato Miyagusuku, Atsushi Yamashita and Hajime Asama: "Dual Monte Carlo Localization Algorithm for Localization Using Wireless Signal Strength Maps", Proceedings of the 6th International Conference on Advanced Mechatronics (ICAM2015), pp. 282-283, Tokyo (Japan), December 2015.
- 140) Jun Younes Louhi (Kasahara), Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Unsupervised Learning Approach to Detection of Void-type Defects in Concrete Structure Using Hammering and Clustering", Proceedings of the 6th International Conference on Advanced Mechatronics (ICAM2015), pp. 319-320, Tokyo (Japan), December 2015.
- 141) Rin Minohara, Wen Wen, Shunsuke Hamasaki, Takaki Maeda, Hiroshi Yamakawa, Satoshi Shibuya, Yukari Ohki, Atsushi Yamashita and Hajime Asama: "Readiness Potential Reflects the Predictive Aspect of

- Sense of Agency", Proceedings of the 6th International Conference on Advanced Mechatronics (ICAM2015), pp. 353-354, Tokyo (Japan), December 2015.
- 142) Soichiro Iwataki, Hiromitsu Fujii, Alessandro Moro, Atsushi Yamashita, Hajime Asama and Hiroshi Yoshinada: "Visualization of the Surrounding Environment and Operational Part in a 3DCG Model for the Teleoperation of Construction Machines", Proceedings of the 2015 IEEE/SICE International Symposium on System Integration (SII2015), pp. 81-87, Nagoya (Japan), December 2015. [doi:10.1109/SII.2015.7404958]
- 143) Akira Shibata, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Absolute Scale Structure from Motion Using a Refractive Plate", Proceedings of the 2015 IEEE/SICE International Symposium on System Integration (SII2015), pp. 540-545, Nagoya (Japan), December 2015. [doi:10.1109/SII.2015.7405037]
- 144) Guanghui Li, Shuiguang Tong, Feiyun Cong, Atsushi Yamashita and Hajime Asama: "Improved Artificial Potential Field-based Simultaneous Forward Search Method for Robot Path Planning in Complex Environment", Proceedings of the 2015 IEEE/SICE International Symposium on System Integration (SII2015), pp. 760-765, Nagoya (Japan), December 2015.
- 145) Shunsuke Hamasaki, Qi An, Wen Wen, Yusuke Tamura, Hiroshi Yamakawa, Atsushi Yamashita, Hajime Asama, Satoshi Unenaka, Satoshi Shibuya and Yukari Ohki: "Influence of Sense of Agency and Sense of Ownership on Body Representation Change of Human Upper Limb", Proceedings of the 1st International Symposium on Embodied-Brain Systems Science (EmboSS2016), p. 26, Tokyo (Japan), May 2016.
- 146) Wen Wen, Atsushi Yamashita and Hajime Asama: "How Agency Influences Ownership and Body Representation", Proceedings of the 1st International Symposium on Embodied-Brain Systems Science (EmboSS2016), p. 27, Tokyo (Japan), May 2016.
- 147) Ningjia Yang, Qi An, Hiroshi Yamakawa, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Muscle Synergy Analysis in Human Standing-up Motion Using Different Strategies", Proceedings of the 1st International Symposium on Embodied-Brain Systems Science (EmboSS2016), p. 32, Tokyo (Japan), May 2016.
- 148) Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Defect Detection with Estimation of Material Condition Using Ensemble Learning for Hammering Test", Proceedings of the 2016 IEEE International Conference on Robotics and Automation (ICRA2016), pp. 3847-3854, Stockholm (Sweden), May 2016. (IEEE Robotics and Automation Society Japan Chapter Young Award) [doi:10.1109/ICRA.2016.7487573]
- 149) Wenzheng Chi, Hitoshi Kono, Yusuke Tamura, Atsushi Yamashita, Hajime Asama and Max Q.-H. Meng: "A Human-friendly Robot Navigation Algorithm Using the Risk-RRT Approach", Proceedings of the 2016 IEEE International Conference on Real-time Computing and Robotics (RCAR2016), pp. 227-232, Angkor Wat (Cambodia), June 2016. (Best Student Paper Award)
- 150) Seungchul Kwak, Yonghoon Ji, Atsushi Yamashita and Hajime Asama: "3-D Reconstruction of Underwater Objects Using Arbitrary Acoustic Views", Proceedings of the 11th France-Japan congress on Mechatronics / the 9th Europe-Asia congress on Mechatronics / the 17th International Conference on Research and Education in Mechatronics (MECATRONICS-REM2016), pp. 74-79, Compiègne (France), June 2016. [doi:10.1109/MECATRONICS.2016.7547119]
- 151) Tatsuya Kittaka, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Creating See-through Image Using Two RGB-D Sensors for Remote Control Robot", Proceedings of the 11th France-Japan congress on Mechatronics / the 9th Europe-Asia congress on Mechatronics / the 17th International Conference on Research and Education in Mechatronics (MECATRONICS-REM2016), pp. 86-91, Compiègne (France), June 2016. [doi:10.1109/MECATRONICS.2016.7547121]
- 152) Hiromasa Kume, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Scale Reconstructable Structure from Motion Using Refraction with Omnidirectional Camera", Proceedings of the 11th France-Japan congress on Mechatronics / the 9th Europe-Asia congress on Mechatronics / the 17th

- International Conference on Research and Education in Mechatronics (MECATRONICS-REM2016), pp. 117-122, Compiègne (France), June 2016. [doi:10.1109/MECATRONICS.2016.7547126]
- 153) Veerachart Srisamosorn, Noriaki Kuwahara, Atsushi Yamashita, Taiki Ogata and Jun Ota: "Design of Face Tracking System Using Environmental Cameras and Flying Robot for Evaluation of Health Care", Proceedings of the 18th International Conference on Human-Computer Interaction (HCI2016), pp. 264-273, Toronto (Canada), July 2016.
- 154) Wen Wen, Atsushi Yamashita and Hajime Asama: "The Influence of Attention on Sense of Agency", The 31st International Congress of Psychology (ICP2016), OR25-32-4, Yokohama (Japan), July 2016.
- 155) Veerachart Srisamosorn, Noriaki Kuwahara, Atsushi Yamashita, Taigi Ogata and Jun Ota: "Design of Face Tracking System Using Fixed 360-Degree Cameras and Flying Blimp for Health Care Evaluation", Proceedings of the 4th International Conference on Serviceology (ICServ2016), pp. 63-66, Tokyo (Japan), September 2016.
- 156) Yuki Ishikawa, Qi An, Wen Wen, Shu Ishiguro, Koji Ohata, Hiroshi Yamakawa, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Auxiliary System to Identify Patterns of Patients with Hemiplegia for Transferring Skill of Rehabilitation with Walking Assist Robot", Proceedings of the 4th International Conference on Serviceology (ICServ2016), pp. 154-157, Tokyo (Japan), September 2016.
- 157) Yonghoon Ji, Seungchul Kwak, Atsushi Yamashita and Hajime Asama: "Acoustic Camera-based 3D Measurement of Underwater Objects through Automated Extraction and Association of Feature Points", Proceedings of the 2016 IEEE International Conference on Multisensor Fusion and Integration for Intelligent Systems (MFI2016), pp. 224-230, Baden-Baden (Germany), September 2016. [doi:10.1109/MFI.2016.7849493]
- 158) Sarthak Pathak, Alessandro Moro, Atsushi Yamashita and Hajime Asama: "A Decoupled Virtual Camera Using Spherical Optical Flow", Proceedings of the 2016 IEEE International Conference on Image Processing (ICIP2016), pp. 4488-4492, Phoenix (USA), September 2016. [doi:10.1109/ICIP.2016.7533209]
- 159) Sarthak Pathak, Alessandro Moro, Atsushi Yamashita and Hajime Asama: "Dense 3D Reconstruction from Two Spherical Images via Optical Flow-based Equirectangular Epipolar Rectification", Proceedings of the 2016 IEEE International Conference on Imaging Systems and Techniques (IST2016), pp. 140-145, Crete Island (Greece), October 2016.
- 160) Hanwool Woo, Yonghoon Ji, Hitoshi Kono, Yusuke Tamura, Atsushi Yamashita, Hajime Asama, Yasuhide Kuroda, Takashi Sugano and Yasunori Yamamoto: "Dynamic Potential-Model-Based Feature for Lane Change Prediction", Proceedings of the 2016 IEEE International Conference on Systems, Man, and Cybernetics (SMC2016), pp. 838-843, Budapest (Hungary), October 2016. [doi:10.1109/SMC.2016.7844344]
- 161) Renato Miyagusuku, Atsushi Yamashita and Hajime Asama: "Gaussian Processes Mappings Improvements Using Path Loss Models for Wireless Signals-based Localization", Proceedings of the 2016 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2016), pp. 4610-4615, Daejeon (Korea), October 2016. [doi:10.1109/IROS.2016.7759678]
- 162) Sarthak Pathak, Alessandro Moro, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "3D Reconstruction of Structures using Spherical Cameras with Small Motion", Proceedings of the 16th International Conference on Control, Automation and Systems (ICCAS2016), pp. 117-122, Gyeongju (Korea), October 2016. (Student Best Paper Award)
- 163) Hanwool Woo, Yonghoon Ji, Hitoshi Kong, Yusuke Tamura, Yasuhide Kuroda, Takashi Sugano, Yasunori Yamamoto, Atsushi Yamashita and Hajime Asama: "Lane-Changing Feature Extraction Using Multisensor Integration", Proceedings of the 16th International Conference on Control, Automation and Systems (ICCAS2016), pp. 1633-1636, Gyeongju (Korea), October 2016.

- 164) Qi An, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "Different Temporal Structure of Muscle Synergy between Sit-to-Walk and Sit-to-Stand Motions in Human Standing Leg", Proceedings of the 3rd International Conference on NeuroRehabilitation (ICNR2016), pp. 933-937, Segovia (Spain), October 2016.
- 165) Doyeon Kim, Hanwool Woo, Yonghoon Ji, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Localization of Radiation Sources Using Gamma-ray Detector in Simulated Environments", Proceedings of the 4th International Conference on Maintenance Science and Technology (ICMST2016), Shenzhen (China), November 2016.
- 166) Rin Minohara, Wen Wen, Shunsuke Hamasaki, Takaki Maeda, Qi An, Yusuke Tamura, Hiroshi Yamakawa, Atsushi Yamashita and Hajime Asama: "How Anticipation for the Sense of Agency Affects Readiness Potential", Proceedings of the 2016 International Symposium on Micro-Nano Mechatronics and Human Science (MHS2016), pp. 166-167, Nagoya (Japan), November 2016. (Best Poster Award)
- 167) Jonghoon Im, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Correction of Over- and Underexposed Images Using Multiple Lighting System for Exploration Robot in Dark Environments", Proceedings of the 2016 IEEE International Conference on Robotics and Biomimetics (ROBIO2016), pp. 375-381, Qingdao (China), December 2016. [doi:10.1109/MFI.2016.7849493]
- 168) Wei Sun, Soichiro Iwataki, Ren Komatsu, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Simultaneous Tele-visualization of Construction Machine and Environment Using Body Mounted Cameras", Proceedings of the 2016 IEEE International Conference on Robotics and Biomimetics (ROBIO2016), pp. 382-387, Qingdao (China), December 2016. [doi:10.1109/ROBIO.2016.7866352]
- 169) Binbin Xu, Sarthak Pathak, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Optical Flow-based Video Completion in Spherical Image Sequences", Proceedings of the 2016 IEEE International Conference on Robotics and Biomimetics (ROBIO2016), pp. 388-395, Qingdao (China), December 2016. [doi:10.1109/ROBIO.2016.7866353]
- 170) Akira Takeuchi, Hiromitsu Fujii, Atsushi Yamashita, Masayuki Tanaka, Ryuho Kataoka, Yoshizumi Miyoshi, Masatoshi Okutomi and Hajime Asama: "3D Visualization of Aurora Considering the Physical Characteristics", Proceedings of ACM SIGGRAPH Asia 2016 Posters, Article No. 52, pp. 1-2, Macao (China), December 2016. [doi:10.1145/3005274.3005285]
- 171) Tsubasa Goto, Sarthak Pathak, Yonghoon Ji, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Spherical Camera Localization in Man-made Environment Using 3D-2D Matching of Line Information", Proceedings of the International Workshop on Advanced Image Technology 2017 (IWAIT2017), Penang (Malaysia), January 2017. (Best Paper Award)
- 172) Yasuyuki Awashima, Ren Komatsu, Hiromitsu Fujii, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Visualization of Obstacles on Bird's-eye View Using Depth Sensor for Remote Controlled Robot", Proceedings of the International Workshop on Advanced Image Technology 2017 (IWAIT2017), Penang (Malaysia), January 2017.
- 173) Yukari Okumura, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Global Optimization with Viewpoint Selection for Scale-reconstructible Structure from Motion Using Refraction", Proceedings of the International Workshop on Advanced Image Technology 2017 (IWAIT2017), Penang (Malaysia), January 2017.
- 174) Hanwool Woo, Yonghoon Ji, Hitoshi Kono, Yusuke Tamura, Yasuhide Kuroda, Takashi Sugano, Yasunori Yamamoto, Atsushi Yamashita and Hajime Asama: "Lane-Change Detection Based on Vehicle-Trajectory Prediction", 2017 IEEE International Conference on Robotics and Automation (ICRA2017), Singapore, May-June 2017. (IEEE Robotics and Automation Letters, Vol. 2, No. 2, pp. 1109-1116, April 2017.)

- 175) Angela Faragasso, Atsushi Yamashita and Hajime Asama: "Versatile Visual-based Touch Sensor for Autonomous Search Robots", Proceedings of the 14th International Conference on Ubiquitous Robots and Ambient Intelligence (URAI2017), pp.282-283, Jeju (Korea), June 2017. [doi:10.1109/URAI.2017.7992730]
- 176) Jonghoon Im, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Multi-Modal Diagnostic Method for Detection of Concrete Crack Direction Using Light-Section Method and Hammering Test", Proceedings of the 14th International Conference on Ubiquitous Robots and Ambient Intelligence (URAI2017), pp. 922-927, Jeju (Korea), June-July 2017. [doi:10.1109/URAI.2017.7992866]
- 177) Ngoc Trung Mai, Hanwool Woo, Yonghoon Ji, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "3-D Reconstruction of Underwater Object Based on Extended Kalman Filter by Using Acoustic Camera Images", Preprints of the 20th World Congress of the International Federation of Automatic Control, pp. 1066-1072, Toulouse (France), July 2017. (IFAC PaperOnLine, Vol. 50, No. 1, pp. 1043-1049, July 2017) [doi:10.1016/j.ifacol.2017.08.215]
- 178) Tasuku Ito, Hitoshi Kono, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Recovery Motion Learning for Arm Mounted Mobile Crawler Robot in Drive System's Failure", Preprints of the 20th World Congress of the International Federation of Automatic Control, pp. 2365-2370, Toulouse (France), July 2017. (IFAC PaperOnLine, Vol. 50, No. 1, pp. 2329-2334, July 2017) [doi:10.1016/j.ifacol.2017.08.475]
- 179) Takao Sugimoto, Hiroshi Yamakawa, Qi An, Wen Wen, Yusuke Tamura, Koichi Ohtomi, Takayuki Kosaka, Hiromasa Suzuki, Atsushi Yamashita and Hajime Asama: "Estimation of Tension and Concentration Scenes during Crane Operation Using Physiological Indices for Skill Improvement Support", Proceedings of the 5th International Conference on Serviceology (ICServ2017), pp. 153-160, Vienna (Austria), July 2017.
- 180) Xiaojun Lu, Angela Faragasso, Yonghoon Ji, Hitoshi Kono, Atsushi Yamashita and Hajime Asama: "Multi-localization Methods for Fault Diagnosis in Autonomous Mobile Robots Systems", Proceedings of the 2017 IEEE International Conference on Real-time Computing and Robotics (RCAR2017), pp. 200-205, Okinawa (Japan), July 2017.
- 181) Yiploon Seow, Renato Miyagusuku, Atsushi Yamashita and Hajime Asama: "Detecting and Solving the Kidnapped Robot Problem Using Laser Range Finder and Wifi Signal", Proceedings of the 2017 IEEE International Conference on Real-time Computing and Robotics (RCAR2017), pp. 303-308, Okinawa (Japan), July 2017.
- 182) Ningjia Yang, Qi An, Hiroshi Yamakawa, Yusuke Tamura, Atsushi Yamashita, Matti Itkonen, Fady Alnajjar, Shingo Shimoda, Hajime Asama, Noriaki Hattori and Ichiro Miyai: "Clarification of Muscle Synergy Structure During Standing-Up Motion of Healthy Young, Elderly and Post-Stroke Patients", Proceedings of the 2017 International Conference on Rehabilitation Robotics (ICORR), pp. 19-24, London (UK), July 2017. [doi:10.1109/ICORR.2017.8009215]
- 183) Jun Jiang, Renato Miyagusuku, Atsushi Yamashita and Hajime Asama: "Glass and Non-Glass Objects Classification Using Laser Rangefinders for Mobile Robots in Indoor Environments", Proceedings of the 2017 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2017), p. 5529, Vancouver (Canada), September 2017.
- 184) Hanwool Woo, Yonghoon Ji, Yusuke Tamura, Yasuhide Kuroda, Takashi Sugano, Yasunori Yamamoto, Atsushi Yamashita and Hajime Asama: "Driver Classification in Vehicle-Following Behavior by Using Dynamic Potential Field Method", Proceedings of the IEEE 20th International Conference on Intelligent Transportation Systems (ITSC2017), pp. 1101-1106, Yokohama (Japan), October 2017.
- 185) Keita Kurashiki, Hiroshi Yoshinada, Keiji Nagatani, Masayuki Tanaka, Atsushi Yamashita, Yasuyoshi Yokokohji and Masashi Konyo: "A Teleoperated Hydraulic Rescue Robot Integrated with Elemental Technologies", Proceedings of the 10th JFPS International Symposium on Fluid Power (JFPS2017), 1C12, pp. 1-4, Fukuoka (Japan), October 2017.

- 186) Masataka Fuchida, Hiroya Yatsuyanagi, Akio Nakamura, Atsushi Yamashita and Hajime Asama: "The Characters Extraction System by a Fingertip for Visually Handicapped People", Proceedings of the 36th JSST Annual International Conference on Simulation Technology (JSST2017), pp. 310-311, Tokyo (Japan), October 2017.
- 187) Renato Miyagusuku, Yiploon Seow, Atsushi Yamashita and Hajime Asama: "Fast and Robust Localization using Laser Rangefinder and WiFi Data", Proceedings of 2017 IEEE International Conference on Multisensor Fusion and Integration for Intelligent Systems (MFI2017), pp. 111-117, Daegu (Korea), November 2017.
- 188) Ngoc Trung Mai, Hanwool Woo, Yonghoon Ji, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "3D Reconstruction of Line Features Using Multi-view Acoustic Images in Underwater Environment", Proceedings of 2017 IEEE International Conference on Multisensor Fusion and Integration for Intelligent Systems (MFI2017), Daegu (Korea), pp. 312-317, November 2017.
- 189) Sonmin Yun, Wen Wen, Qi An, Shunsuke Hamasaki, Hiroshi Yamakawa, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Investigating the Relationship between Driver's Sense of Agency and EEG: Mu-rhythm is More Suppressed in Higher SoA Case", Proceedings of the 2017 International Symposium on Micro-Nano Mechatronics and Human Science (MHS2017), pp. 272-276, Nagoya (Japan), December 2017.
- 190) Yasuyuki Awashima, Hiromitsu Fujii, Yusuke Tamura, Keiji Nagatani, Atsushi Yamashita and Hajime Asama: "Safeness Visualization of Terrain for Teleoperation of Mobile Robot Using 3D Environment Map and Dynamic Simulator", Proceedings of the 2017 IEEE/SICE International Symposium on System Integration (SII2017), pp. 194-200, Taipei (Taiwan), December 2017. [doi:10.1109/SII.2017.8279211]
- 191) Yuyang Shao, Yonghoon Ji, Hiromitsu Fujii, Keiji Nagatani, Atsushi Yamashita and Hajime Asama: "Estimation of Scale and Slope Information for Structure from Motion-based 3D Map", Proceedings of the 2017 IEEE/SICE International Symposium on System Integration (SII2017), pp. 208-213, Taipei (Taiwan), December 2017. [doi:10.1109/SII.2017.8279213]
- 192) Jun Jiang, Renato Miyagusuku, Atsushi Yamashita and Hajime Asama: "Glass Confidence Maps Building Based on Neural Networks Using Laser Range-finders for Mobile Robots", Proceedings of the 2017 IEEE/SICE International Symposium on System Integration (SII2017), pp. 405-410, Taipei (Taiwan), December 2017. [doi:10.1109/SII.2017.8279246]
- 193) Doyeon Kim, Hanwool Woo, Yonghoon Ji, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "3D Radiation Imaging Using Mobile Robot Equipped with Radiation Detector", Proceedings of the 2017 IEEE/SICE International Symposium on System Integration (SII2017), pp. 444-449, Taipei (Taiwan), December 2017. [doi:10.1109/SII.2017.8279253]
- 194) Jun Younes Louhi Kasahara, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Clustering of Spatially Relevant Audio Data using Mel-Frequency Cepstrum for Diagnosis of Concrete Structure by Hammering Test", Proceedings of the 2017 IEEE/SICE International Symposium on System Integration (SII2017), pp. 787-792, Taipei (Taiwan), December 2017. [doi:10.1109/SII.2017.8279318]
- 195) Sarthak Pathak, Alessandro Moro, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Virtual Reality with Motion Parallax by Dense Optical Flow-based Depth Generation from Two Spherical Images", Proceedings of the 2017 IEEE/SICE International Symposium on System Integration (SII2017), pp. 887-892, Taipei (Taiwan), December 2017. [doi:10.1109/SII.2017.8279335]
- 196) Hiroki Kogami, Qi An, Ningjia Yang, Hiroshi Yamakawa, Yusuke Tamura, Atsushi Yamashita, Hajime Asama, Shingo Shimoda, Hiroshi Yamasaki, Matti Itkonen, Fady Alnajjar, Noriaki Hattori, Makoto Kinomoto, Kouji Takahashi, Takanori Fujii, Hironori Otomune and Ichiro Miyai: "Effect of Physical Therapy on Muscle Synergy Structure during Standing-up Motion of Hemiplegic Patients", Proceedings of the 2018 IEEE International Conference on Robotics and Automation (ICRA2018), Brisbane (Australia),

May 2018. (IEEE Robotics and Automation Letters, Vol. 3, No. 3, pp. 2229-2236, July 2018.)

- 197) Tsubasa Goto, Sarthak Pathak, Yonghoon Ji, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Line-based Global Localization of a Spherical Camera in Manhattan Worlds", Proceedings of the 2018 IEEE International Conference on Robotics and Automation (ICRA2018), pp. 2296-2303, Brisbane (Australia), May 2018. [doi:10.1109/ICRA.2018.8460920]
- 198) Ngoc Trung Mai, Yonghoon Ji, Hanwool Woo, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Acoustic Image Simulator Based on Active Sonar Model in Underwater Environment", Proceedings of the 15th International Conference on Ubiquitous Robots (UR2018), pp. 775-780, Honolulu (USA), June 2018. [doi:10.1109/URAI.2018.8441870]
- 199) Angela Faragasso, Joao Bimbo, Atsushi Yamashita and Hajime Asama: "Disposable Stiffness Sensor for Endoscopic Examination", Proceedings of the 40th Annual International Conference of the IEEE Engineering in Medicine and Biology Society (EMBC2018), pp. 4309-4312, Honolulu (USA), July 2018. [doi:10.1109/EMBC.2018.8513350]
- 200) Yusheng Wang, Yonghoon Ji, Hanwool Woo, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "3D Occupancy Mapping Framework Based on Acoustic Camera in Underwater Environment", Preprints of the 12th IFAC Symposium on Robot Control (SYROCO2018), Paper No. 055, pp. 1-7, Budapest (Hungary), August 2018.
- 201) Stefano Massaroli, Renato Myagusuku, Federico Califano, Claudio Melchiorri, Atsushi Yamashita and Hajime Asama: "Recursive Algebraic Frisch Scheme: a Particle-Based Approach", Preprints of the Joint 9th IFAC Symposium on Robust Control Design (ROCOND2018) and 2nd IFAC Workshop on Linear Parameter Varying Systems (LPVS2018), pp. 599-605, Florianopolis (Brazil), September 2018.
- 202) Masataka Fuchida, Shota Chikushi, Alessandro Moro, Atsushi Yamashita and Hajime Asama: "Arbitrary Viewpoint Visualization for Disaster Response Robots", Proceedings of the 37th JSST Annual International Conference on Simulation Technology (JSST2018), Muroran (Japan), September 2018.
- 203) Tatsuya Kittaka, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Real-time Registration of RGB-D Image Pair for See-through System", Proceedings of the 2018 IEEE International Conference on Image Processing (ICIP2018), pp. 1233-1237, Athens (Greece), October 2018. [doi:10.1109/ICIP.2018.8451512]
- 204) Sarthak Pathak, Alessandro Moro, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Distortion-Robust Spherical Camera Motion Estimation via Dense Optical Flow", Proceedings of the 2018 IEEE International Conference on Image Processing (ICIP2018), pp. 3358-3362, Athens (Greece), October 2018. [doi:10.1109/ICIP.2018.8451406]
- 205) Sonmin Yun, Wen Wen, Qi An, Shunsuke Hamasaki, Hiroshi Yamakawa, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Investigating the Relationship between Assisted Driver's SoA and EEG", Proceedings of the 5th International Conference on NeuroRehabilitation (ICNR2018), pp. 1039-1043, Pisa (Italy), October 2018. [doi:10.1007/978-3-030-01845-0\_208]
- 206) Hanwool Woo, Yonghoon Ji, Yusuke Tamura, Yasuhide Kuroda, Takashi Sugano, Yasunori Yamamoto, Atsushi Yamashita and Hajime Asama: "Advanced Adaptive Cruise Control Based on Collision Risk Assessment", Proceedings of the 21st IEEE International Conference on Intelligent Transportation Systems (ITSC2018), pp. 939-944, Maui (USA), November 2018. [doi:10.1109/ITSC.2018.8569759]
- 207) Ryu Ohata, Wen Wen, Atsushi Yamashita, Hajime Asama and Hiroshi Imamizu: "Dissociative Processes for Detecting Change in Control", Proceedings of the 2nd International Symposium on Embodied-Brain Systems Science (EmboSS2018), P44, p. 1, Osaka (Japan), December 2018.
- 208) Qi An, Hiroki Kogami, Ningjia Yang, Hiroshi Yamakawa, Yusuke Tamura, Hiroshi Yamasaki, Matti Ikonen, Fady Shibata-Alnajjar, Shingo Shimoda, Noriaki Hattori, Makoto Kinomoto, Kouji Takahashi,

- Takanori Fujii, Hironori Otomune, Ichiro Miyai, Atsushi Yamashita and Hajime Asama: "Rehabilitation Intervention of Physical Therapists Improves Muscle Synergy during Standing-up Motion of Stroke Patients", Proceedings of the 2nd International Symposium on Embodied-Brain Systems Science (EmboSS2018), P49, p. 1, Osaka (Japan), December 2018.
- 209) Ningjia Yang, Qi An, Hiroshi Yamakawa, Yusuke Tamura, Kouji Takahashi, Makoto Kinomoto, Hiroshi Yamasaki, Matti Itkonen, Fady Shibata-Alnajjar, Shingo Shimoda, Noriaki Hattori, Takanori Fujii, Hironori Otomune, Ichiro Miyai, Atsushi Yamashita and Hajime Asama: "Clarification of Altered Muscle Synergies during Sit-to-stand Motion in Stroke Patients", Proceedings of the 2nd International Symposium on Embodied-Brain Systems Science (EmboSS2018), P50, p. 1, Osaka (Japan), December 2018.
- 210) Hiroki Kogami, Qi An, Ningjia Yang, Hiroshi Yamakawa, Yusuke Tamura, Hiroshi Yamasaki, Matti Itkonen, Fady Shibata-Alnajjar, Shingo Shimoda, Noriaki Hattori, Makoto Kinomoto, Kouji Takahashi, Takanori Fujii, Hironori Otomune, Ichiro Miyai, Atsushi Yamashita and Hajime Asama: "Effect of Physical Therapy on Joint Angle of Hemiplegic Patients during Standing-up Motion", Proceedings of the 2nd International Symposium on Embodied-Brain Systems Science (EmboSS2018), P51, p. 1, Osaka (Japan), December 2018.
- 211) Shunsuke Hamasaki, Atsushi Yamashita and Hajime Asama: "Investigation of the Influence of Sense of Ownership and Agency on Three-Dimensional Change of Body Representation of Upper Limb", Proceedings of the 2nd International Symposium on Embodied-Brain Systems Science (EmboSS2018), P57, p. 1, Osaka (Japan), December 2018.
- 212) Sonmin Yun, Wen Wen, Qi An, Shunsuke Hamasaki, Hiroshi Yamakawa, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Investigating the Relationship between Assisted Driver's Sense of Agency and EEG Alpha Power", Proceedings of the 2nd International Symposium on Embodied-Brain Systems Science (EmboSS2018), P66, p. 1, Osaka (Japan), December 2018.
- 213) Kei Aoyagi, Wen Wen, Qi An, Shunsuke Hamasaki, Hiroshi Yamakawa, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Improvement of Sense of Agency via Visual Intervention in Virtual Reality", Proceedings of the 2nd International Symposium on Embodied-Brain Systems Science (EmboSS2018), P73, p. 1, Osaka (Japan), December 2018.
- 214) Shunsuke Hamasaki, Atsushi Yamashita and Hajime Asama: "A Three-Dimensional Evaluation of Body Representation Change of Human Upper Limb Focused on Sense of Ownership and Sense of Agency", Proceedings of the 2018 International Symposium on Micro-Nano Mechatronics and Human Science (MHS2018), pp. 259-262, Nagoya (Japan), December 2018.
- 215) Sarthak Pathak, Alessandro Moro, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Distortion-Resistant Spherical Visual Odometry for UAV-Based Bridge Inspection", Proceedings of SPIE, Vol. 11049 (Proceedings of the 2019 Joint Conference of the International Workshop on Advanced Image Technology (IWAIT2019) and the International Forum on Medical Imaging in Asia (IFMIA2019)), pp. 110491O-1-110491O-6, Singapore (Singapore), January 2019. [doi:10.1117/12.2520206]
- 216) Momoko Kawata, Hiroshi Higuchi, Hiromitsu Fujii, Atsushi Taniguchi, Masahiro Watanabe, Atsushi Yamashita and Hajime Asama: "Acceleration of 3D Measurement of Large Structures with Ring Laser and Camera via FFT-based Template Matching", Proceedings of the 2019 IEEE/SICE International Symposium on System Integration (SII2019), pp. 11-16, Paris (France), January 2019. [doi:10.1109/SII.2019.8700345]
- 217) Yusheng Wang, Yonghoon Ji, Hanwool Woo, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Three-dimensional Underwater Environment Reconstruction with Graph Optimization Using Acoustic Camera", Proceedings of the 2019 IEEE/SICE International Symposium on System Integration (SII2019), pp. 28-33, Paris (France), January 2019. [doi:10.1109/SII.2019.8700464]
- 218) Irem Uygur, Renato Miyagusuku, Sarthak Pathak, Alessandro Moro, Atsushi Yamashita and Hajime



- Asama: "A Framework for Bearing-Only Sparse Semantic Self-Localization for Visually Impaired People", Proceedings of the 2019 IEEE/SICE International Symposium on System Integration (SII2019), pp. 319-324, Paris (France), January 2019. [doi:10.1109/SII.2019.8700370]
- 219) Momoko Kawata, Hiroshi Higuchi, Hiromitsu Fujii, Atsushi Taniguchi, Masahiro Watanabe, Atsushi Yamashita and Hajime Asama: "Acceleration of 3D Measurement of Large Structures with Ring Laser and Camera via FFT-based Template Matching", 2019 IEEE International Conference on Computational Photography (ICCP2019), May 2019.
- 220) Hiroshi Higuchi, Hiromitsu Fujii, Atsushi Taniguchi, Masahiro Watanabe, Atsushi Yamashita and Hajime Asama: "Speckle Based Pose Estimation Considering Depth Information for 3D Measurement of Texture-less Environment", 2019 IEEE International Conference on Computational Photography (ICCP2019), May 2019.
- 221) Dabae Kim, Sarthak Pathak, Alessandro Moro, Ren Komatsu, Atsushi Yamashita and Hajime Asama: "E-CNN: Accurate Spherical Camera Rotation Estimation via Uniformization of Distorted Optical Flow Fields", Proceedings of the 2019 IEEE International Conference on Acoustics, Speech, and Signal Processing (ICASSP2019), pp. 2232-2236, Brighton (UK), May 2019. [doi:10.1109/ICASSP.2019.8682203]
- 222) Yonghoon Ji, Atsushi Yamashita, Kazunori Umeda and Hajime Asama: "Automatic Camera Pose Estimation based on a Flat Surface Map", Proceedings of SPIE, Vol. 11172 (Proceedings of the 15th International Conference on Quality Control by Artificial Vision (QCAV2019)), pp. 111720X-1-111720X-6, Mulhouse (France), May 2019. [doi:10.1117/12.2521780]
- 223) Renato Miyagusuku, Atsushi Yamashita and Hajime Asama: "Data Information Fusion from Multiple Access Points for WiFi-based Self-localization", Proceedings of the 2019 IEEE International Conference on Robotics and Automation (ICRA2019), Montreal (Canada), May 2019. (IEEE Robotics and Automation Letters, Vol. 4, No. 2, pp. 269-276, April 2019.) (IEEE Robotics and Automation Society Japan Joint Chapter Young Award)
- 224) Xiaorui Qiao, Atsushi Yamashita and Hajime Asama: "3D Reconstruction for Underwater Investigation at Fukushima Daiichi Nuclear Power Station Using Refractive Structure from Motion", International Topical Workshop on Fukushima Decommissioning Research (FDR2019), FDR2019-1006, pp. 1-4, Fukushima (Japan), May 2019. (FDR2019 Selected Paper)
- 225) Stefano Massaroli, Renato Miyagusuku, Federico Califano, Angela Faragasso, Atsushi Yamashita and Hajime Asama: "A Novel Recursive Linear Estimator Based on the Frisch Scheme", Proceedings of the 2019 12th Asian Control Conference (ASCC2019), pp. 1101-1106, Kitakyushu (Japan), June 2019.
- 226) Wen Wen, Ryu Ohata, Masaru Tanaka, Atsushi Yamashita, Hajime Asama and Hiroshi Imamizu: "Two Dissociable Processes for Detecting Gaining and Losing Control in Human Brain", 23rd Annual Meeting of the Association for the Scientific Study of Consciousness (ASSC23), London Ontario (Canada), June 2019.
- 227) Jun Jiang, Renato Miyagusuku, Atsushi Yamashita and Hajime Asama: "Robust Map Registration for Building Online Glass Confidence Maps", Proceedings of the 10th IFAC Symposium on Intelligent Autonomous Vehicles (IAV2019), pp. 362-367, Gdansk (Poland), July 2019. (IFAC PaperOnLine, Vol. 52, No. 8, pp. 362-367, September 2019) [doi:10.1016/j.ifacol.2019.08.108]
- 228) Kei Aoyagi, Wen Wen, Qi An, Shunsuke Hamasaki, Hiroshi Yamakawa, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Improvement of Sense of Agency During Upper-Limb Movement for Motor Rehabilitation Using Virtual Reality", Proceedings of the 41st Annual International Conference of the IEEE Engineering in Medicine and Biology Society (EMBC2019), pp. 118-121, Berlin (Germany), July 2019. [doi:10.1109/EMBC.2019.8856796]
- 229) Yusheng Wang, Yonghoon Ji, Hanwool Woo, Yusuke Tamura, Hiroshi Tsuchiya, Atsushi Yamashita and Hajime Asama: "Rotation Estimation of Acoustic Camera Based on Illuminated Area in Acoustic Image",

- Preprints of the Joint 12th IFAC Conference on Control Applications in Marine Systems, Robotics, and Vehicles (CAMS2019), pp. 217-222, Daejeon (Korea), September 2019.
- 230) Stefano Massaroli, Federico Califano, Angela Faragasso, Atsushi Yamashita and Hajime Asama: "Iterative Energy Shaping of a Ball-Dribbling Robot", Preprints of the 1st IFAC Workshop on Robot Control (WROCO2019), pp. 248-253, Daejeon (Korea), September 2019. (Young Author Award)
- 231) Xiaorui Qiao, Yonghoon Ji, Atsushi Yamashita and Hajime Asama: "Structure from Motion of Underwater Scenes Considering Image Degradation and Refraction", Preprints of the 1st IFAC Workshop on Robot Control (WROCO2019), pp. 455-459, Daejeon (Korea), September 2019.
- 232) Shinya Katsuma, Hanwool Woo, Yonghoon Ji, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Efficient Motion Planning for Mobile Robots Dealing with Changes in Rough Terrain", Preprints of the 1st IFAC Workshop on Robot Control (WROCO2019), pp. 460-463, Daejeon (Korea), September 2019.
- 233) Hiroki Kogami, Qi An, Hiroshi Yamakawa, Ningjia Yang, Yusuke Tamura, Hiroshi Yamasaki, Fady Alnajjar, Shingo Shimoda, Makoto Kinomoto, Noriaki Hattori, Kouji Takahashi, Takanori Fujii, Hironori Otomune, Ichiro Miyai, Shu Ishiguro, Takashi Saigusa, Yoshikazu Nozaki, Haruhisa Maruyama, Atsushi Yamashita and Hajime Asama: "Assistive Chair to Support Hip Rising of Elderly People Improves Body Movement of Sit-To-Stand Motion", Preprints of the 1st IFAC Workshop on Robot Control (WROCO2019), pp. 480-483, Daejeon (Korea), September 2019.
- 234) Hanwool Woo, Hirokazu Madokoro, Kazuhito Sato, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Advanced Adaptive Cruise Control Considering Reaction Time of Following Driver", Proceedings of the 2019 IEEE 8th Global Conference on Consumer Electronics (GCCE2019), pp. 995-996, Osaka (Japan), October 2019.
- 235) Jun Younes Louhi Kasahara, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Weakly Supervised Approach to Defect Detection in Concrete Structures Using Hammering Test", Proceedings of the 2019 IEEE 8th Global Conference on Consumer Electronics (GCCE2019), pp. 997-998, Osaka (Japan), October 2019.
- 236) Norihiro Yamauchi, Shota Chikushi, Yusuke Tamura, Hiroshi Yamakawa, Keiji Nagatani, Hiromitsu Fujii, Yuya Sakai, Takumi Chiba, Shingo Yamamoto, Kazuhiro Chayama, Atsushi Yamashita and Hajime Asama: "Estimation of Cone Index from Water Content and Soil Types Obtained from Hyperspectral Images", Proceedings of the 2019 IEEE 8th Global Conference on Consumer Electronics (GCCE2019), pp. 999-1002, Osaka (Japan), October 2019.
- 237) Lei Jiang, Hiroshi Higuchi, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Robust Reflection Removal Against Accumulated Error by Using Stereo Camera System", Proceedings of the 2019 IEEE 8th Global Conference on Consumer Electronics (GCCE2019), pp. 1003-1004, Osaka (Japan), October 2019.
- 238) Wanqi Yin, Sarthak Pathak, Alessandro Moro, Atsushi Yamashita and Hajime Asama: "Improving 3D Measurement Accuracy in Epipolar Directions via Trinocular Spherical Stereo", Proceedings of the 2019 IEEE 8th Global Conference on Consumer Electronics (GCCE2019), pp. 1005-1006, Osaka (Japan), October 2019.
- 239) Runqiu Bao, Ren Komatsu, Renato Miyagusuku, Masaki Chino, Atsushi Yamashita and Hajime Asama: "Cost-effective and Robust Visual Based Localization with Consumer-level Cameras at Construction Sites", Proceedings of the 2019 IEEE 8th Global Conference on Consumer Electronics (GCCE2019), pp. 1007-1009, Osaka (Japan), October 2019.
- 240) Stefano Massaroli, Federico Califano, Angela Faragasso, Atsushi Yamashita and Hajime Asama: "Energy-Based Hybrid Control of a Ball-Dribbling Robot", Proceedings of the 2019 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS2019), p. 3370, Macau (China), November 2019.
- 241) Stefano Massaroli, Federico Califano, Claudio Melchiorri, Atsushi Yamashita and Hajime Asama: "A

- Novel Identification Procedure for Dynamic Parameters of Robots: the Frisch Scheme Approach", Proceedings of the 15th European Workshop on Advanced Control and Diagnosis (ACD2019), FrD2.7, Bologna (Italy), November 2019.
- 242) Wanqi Yin, Sarthak Pathak, Alessandro Moro, Atsushi Yamashita and Hajime Asama: "Accurate All-round 3D Measurement Using Trinocular Spherical Stereo via Weighted Reprojection Error Minimization", Proceedings of the 21st IEEE International Symposium on Multimedia (ISM2019), pp. 86-93, San Diego (USA), December 2019. [doi:10.1109/ISM.2019.00021]
- 243) Stefano Massaroli, Michael Poli, Federico Califano, Angela Faragasso, Jinkyoo Park, Atsushi Yamashita and Hajime Asama: "Port-Hamiltonian Approach to Neural Network Training", Proceedings of the 2019 IEEE Conference on Decision and Control (CDC2019), pp. 6799-6806, Nice (France), December 2019.
- 244) Daisuke Uchida, Atsushi Yamashita and Hajime Asama: "Detecting Image Frames which Contain a Moving Object from a Severely Distorted Video Stream Using Dynamic Mode Decomposition", Proceedings of the International Workshop on Advanced Image Technology 2020 (IWAIT2020), Yogyakarta (Indonesia), January 2020.
- 245) Hiroshi Higuchi, Hiromitsu Fujii, Atsushi Taniguchi, Masahiro Watanabe, Atsushi Yamashita and Hajime Asama: "Speckle Based Pose Estimation for 3D Measurement of the Feature-less Environment by Two Cameras", Proceedings of the International Workshop on Advanced Image Technology 2020 (IWAIT2020), Yogyakarta (Indonesia), January 2020.
- 246) Weijie Chen, Sarthak Pathak, Alessandro Moro, Atsushi Yamashita and Hajime Asama: "Extrinsic Parameters Calibration of Multiple Fisheye Cameras in Manhattan Worlds", Proceedings of the International Workshop on Advanced Image Technology 2020 (IWAIT2020), Yogyakarta (Indonesia), January 2020.
- 247) Jun Younes Louhi Kasahara, Hiromitsu Fujii, Atsushi Yamashita and Hajime Asama: "Complementarity of Sensors and Weak Supervision for Defect Detection in Concrete Structures", Proceedings of the 2020 IEEE/SICE International Symposium on System Integration (SII2020), pp. 1-6, Honolulu (USA), January 2020. (Best Paper Award) [doi:10.1109/SII46433.2020.9026304]
- 248) Shota Chikushi, Yushi Moriyama, Hiromitsu Fujii, Yusuke Tamura, Hiroshi Yamakawa, Keiji Nagatani, Yuya Sakai, Takumi Chiba, Shingo Yamamoto, Kazuhiro Chayama, Atsushi Yamashita and Hajime Asama: "Automated Image Presentation for Backhoe Embankment Construction in Unmanned Construction Site", Proceedings of the 2020 IEEE/SICE International Symposium on System Integration (SII2020), pp. 22-27, Honolulu (USA), January 2020. [doi:10.1109/SII46433.2020.9026298]
- 249) Hanwool Woo, Hirokazu Madokoro, Sato Kazuhito, Yusuke Tamura, Atsushi Yamashita and Hajime Asama: "Prediction of Following Vehicle Trajectory Considering Operation Characteristics of a Human Driver", Proceedings of the 2020 IEEE/SICE International Symposium on System Integration (SII2020), pp. 712-717, Honolulu (USA), January 2020. [doi:10.1109/SII46433.2020.9026243]
- 250) Michael Poli, Stefano Massaroli, Junyoung Park, Atsushi Yamashita, Hajime Asama and Jinkyoo Park: "Graph Neural Ordinary Differential Equations", Proceedings of the 1st International Workshop on Deep Learning on Graphs: Methodologies and Applications (DLGMA2020), New York (USA), February 2020.
- 251) Stefano Massaroli, Michael Poli, Sanzhar Bakhtiyarov, Jinkyoo Park, Atsushi Yamashita and Hajime Asama: "Neural Ordinary Differential Equation Value Networks for Parametrized Action Spaces", Eighth International Conference on Learning Representations (ICLR2020) Workshop on Integration of Deep Neural Models and Differential Equations, Addis Ababa (Ethiopia), April 2020.
- 252) Michael Poli, Stefano Massaroli, Atsushi Yamashita, Hajime Asama and Jinkyoo Park: "Port-Hamiltonian Gradient Flows", Eighth International Conference on Learning Representations (ICLR2020) Workshop on Integration of Deep Neural Models and Differential Equations, Addis Ababa

(Ethiopia), April 2020.

- 253) Ningjia Yang, Qi An, Hiroki Kogami, Kazunori Yoshida, Hiroshi Yamakawa, Yusuke Tamura, Shingo Shimoda, Hiroshi Yamasaki, Moeka Sonoo, Matti Itkonen, Fady Alnajjar, Noriaki Hattori, Makoto Kinomoto, Kouji Takahashi, Takanori Fujii, Hironori Otomune, Ichiro Miyai, Atsushi Yamashita and Hajime Asama: "Temporal Muscle Synergy Features Estimate Effects of Short-term Rehabilitation in Sit-to-stand of Post-stroke Patients", Proceedings of the 2020 IEEE International Conference on Robotics and Automation (ICRA2020), Paris (France), May 2020. (IEEE Robotics and Automation Letters, Vol. 5, No. 2, pp. 1796-1802, April 2020.)
- 254) Stefano Massaroli, Federico Califano, Angela Faragasso, Mattia Risiglione, Atsushi Yamashita and Hajime Asama: "Identification of a Class of Hybrid Dynamical Systems", Preprints of the 21st World Congress of the International Federation of Automatic Control, Berlin (Germany), July 2020.
- 255) Stefano Massaroli, Federico Califano, Angela Faragasso, Atsushi Yamashita and Hajime Asama: "Multistable Energy Shaping of Passive Linear Systems with Hybrid Mode Selector", Preprints of the 21st World Congress of the International Federation of Automatic Control, Berlin (Germany), July 2020.
- 256) Yusheng Wang, Yonghoon Ji, Hanwool Woo, Yusuke Tamura, Hiroshi Tsuchiya, Atsushi Yamashita and Hajime Asama: "Planar AnP: A Solution to Acoustic-n-Point Problem on Planar Target", OCEANS2020, Singapore (Singapore), August 2020.

(Last Modified: April 3, 2020)